

Multiphasic equations for a NWP system

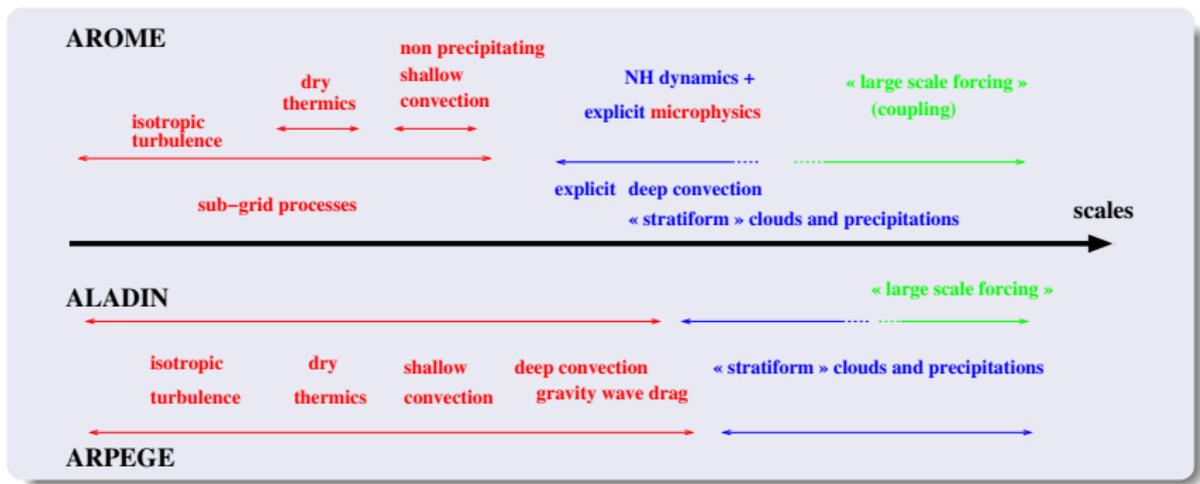
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Resolved versus parametrised processes



Clouds in NWP models

Large scale physics

For « large scale » model, we usually suppose(d) that a diagnostic representation of condensates is enough (no condensates in the air state forecasted by the model).

- We use diagnostic formulation from the mean water vapor content when needed (radiation, output)
- As the condensates (cloud and rain) are not pronostic, they are not directly known by the dynamics : no advection, no inertia, no weight of condensates

Clouds in NWP models

Cloud scale physics

In order to solve explicitly clouds formation and life cycle, we need a NH-dynamics, but also a finer description of microphysics processes.

- Explicit (pronostic) evolution equations for condensates (multiphasic system)
- Interaction between condensates and the dynamics (advection, weight of condensed phases)
- **Realistic sedimentation (precipitation) with « finite » falling velocity (precipitating species are a component of an air parcel)**
- **Detailed microphysics with a complete phase transition description (see J. P. Pinty's talk)**

Large scale physics / cloud scale physics in practice

Water phase changes in a « large scale » physics

- equations for gaseous species only
- cond/evap with the pseudo-adiabatic hypothesis (no condensed phase in the atmosphere, precipitations are known only through their consequences on T and q_v)

$$\frac{\partial \rho_v}{\partial t} = \frac{\partial P}{\partial z}$$

Water phase changes in a cloud scale physics

- equations for gases and condensates
- parametrisation of detailed microphysical processes (but there may still be problem with unresolved clouds)

$$\frac{\partial \rho_v}{\partial t} = - \frac{\partial(\rho_c + \rho_r)}{\partial z} + \frac{\partial P}{\partial z}$$

Large scale physics / cloud scale physics

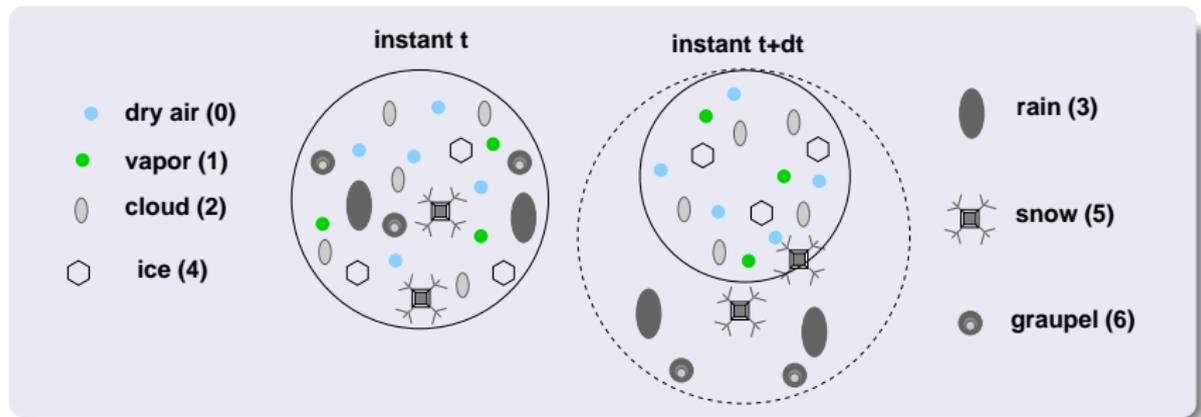
Our worry

To have a consistent set of equations with hypotheses and approximations « under control » and valid for pseudo-adiabatic or multiphase, ($\delta m = 0$ or $\delta m = 1$), hydrostatic or non-hydrostatic **NWP** model.

Warnings

It is a « burning » subject with recent references only

The multiphasic system of Arome



Questions

Variables in a multiphasic atmospheric parcel

- Which ρ ?
- Which p and T ?
- Which wind? What velocities should we manipulate?
- Advection of what by what?

How can we treat condensates?

- As individuals with their own evolution laws?
- As continuous components of a mixture?

The local scale (our scale of the continuum)

A continuum of droplets and drops

$$\rho_c = \frac{m_c}{V_{\text{gaz}}} \quad \rho_r = \frac{m_r}{V_{\text{gaz}}}$$

$$\rho = \sum_k \rho_k$$

Local equilibrium hypothesis

$$T_{\text{eq}} = T_c = T_r = T_{\text{gaz}}$$

$$\vec{v}_{\text{eq}} = \vec{v}_c = \vec{v}_r = \vec{v}_{\text{gaz}}$$

Barycentric parameter at the local scale

Barycentric formulation

$$\rho\psi = \sum_l \rho_l \psi_l \quad \text{or} \quad \psi = \sum_l q_l \psi_l$$

$$\text{local departure : } \tilde{\psi}_l = \psi_l - \psi$$

Consequences of equilibrium hypotheses

$$\vec{v} = \sum_l q_l \vec{v}_l = \left(\sum_l q_l \right) \vec{v}_{eq} = \vec{v}_{eq}$$

$$h = \sum_l q_l h_l = \left(\sum_l q_l h_l^\circ \right) + \left(\sum_l q_l c_{p,l} \right) T = h^\circ + c_p T$$

$$\text{with } c_p = \sum_l q_l c_{p,l}$$

Averaging from the local scale to the model scale

Volumic averaging

$$\bar{\psi} = \frac{1}{V} \int_V \psi dv$$

with $\psi' = \psi - \bar{\psi}$ and $\bar{\psi}' = 0$

Mass-weighted averaging

$$\hat{\psi} = \frac{1}{m} \int_m \psi dm$$

with $\psi'' = \psi - \hat{\psi}$ and $\hat{\psi}'' = 0$

Averaging in a multiphase system

Averaging are weighted by the volume or the mass of the mixture

Volumic averaging

$$\bar{\psi} = \frac{1}{V} \int_V \psi dv$$

$$\bar{\psi}_l = \frac{1}{V} \int_V \psi_l dv$$

Averaging in a multiphasic system

Mass-weighted averaging of a barycentric parameter

$$\hat{\psi} = \frac{1}{m} \int_m \psi dm = \frac{1}{m} \int_V \rho \psi dv$$

Mass-weighted averaging of a parameter for the species l

$$\hat{\psi}_l = \frac{1}{m} \int_m \psi_l dm = \frac{1}{m} \int_V \rho \psi_l dv$$

with

$$\psi_l = \hat{\psi}_l + \psi_l''$$

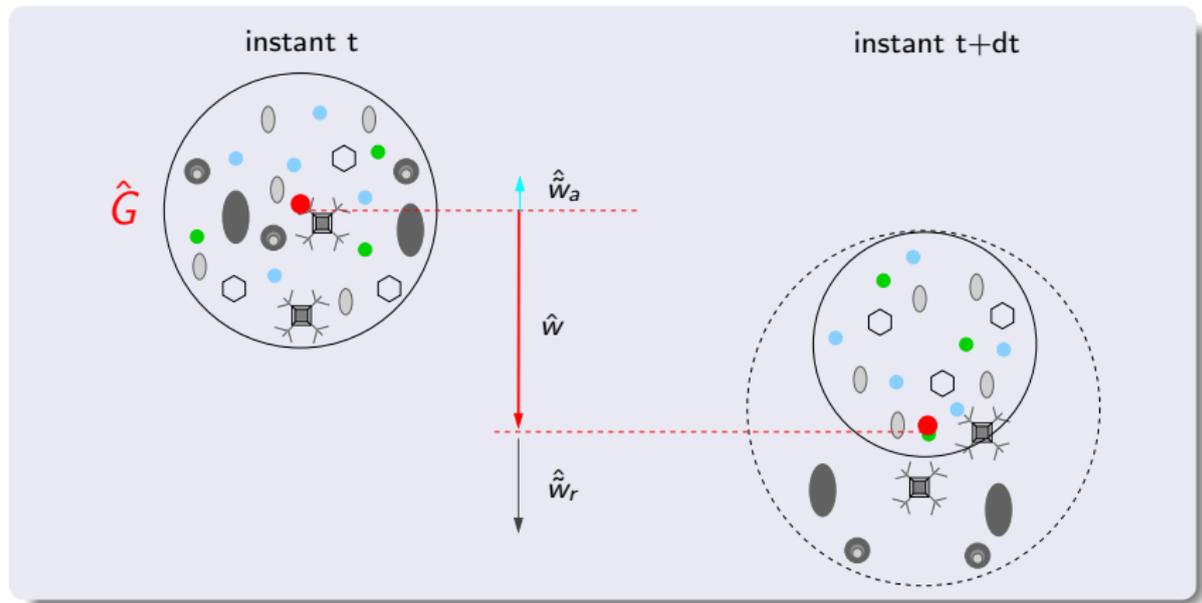
but

$$\psi_l = \hat{\psi} + \psi_l'''$$

and

$$\hat{\psi}_l''' = \hat{\psi}_l - \hat{\psi} = \hat{\psi}_l \neq 0$$

Example



State equation at local scale

An equation for perfect gaz only

$$p = p_a + e = \rho_a R_a T + \rho_v R_v T$$

or

$$p = \rho R_h T$$

with $R_h = q_a R_a + q_v R_v$ and $q_a = \rho_a / \rho$, $q_v = \rho_v / \rho$

State equation at the model scale

Mean state equations for dry air and water vapor

$$\begin{aligned}\bar{p}_a &= \bar{\rho} \hat{q}_a R_a \hat{T} + R_a \overline{\rho q_a'' T''} \\ \bar{e} &= \bar{\rho} \hat{q}_v R_v \hat{T} + R_v \overline{\rho q_v'' T''}\end{aligned}$$

Hypothesis

To conserve the shape of the gaz state law, we have to neglect non-linear terms

$$\bar{p} = \bar{p}_a + \bar{e} = \bar{\rho} (R_a \hat{q}_a + R_v \hat{q}_v) \hat{T}$$

Total mass conservation

Budget of mass in any geometric volum V

$$\frac{\partial m}{\partial t} = \frac{\partial (\int_V \rho dv)}{\partial t} = - \int_S \sum_l (\rho_l \vec{u}_l \cdot \vec{n}) dS + \int_V \sum_l \dot{\rho}_l dv$$

No mass source at the local scale

$$\sum_l \dot{\rho}_l = 0$$

Continuity equation

Eulerian form of the local multiphasic continuity equation

$$\frac{\partial \rho}{\partial t} = -\text{div}(\rho \vec{u})$$

Eulerian form of the average multiphasic continuity equation

$$\frac{\partial \bar{\rho}}{\partial t} = -\text{div}(\bar{\rho} \vec{u}) = -\text{div}(\bar{\rho} \hat{u})$$

An alternative : dry air conservation (Bannon, 2002)

Budget of dry air in a geometric volum V

$$\frac{\partial m_a}{\partial t} = \frac{\partial (\int_V \rho_a dv)}{\partial t} = - \int_S \rho_a \vec{u}_a \cdot \vec{n} dS + \int_V \dot{\rho}_a dv$$

No dry air source

$$\dot{\rho}_a = 0$$

Eulerian form of the dry air continuity equation

$$\frac{\partial \rho_a}{\partial t} = -\text{div}(\rho_a \vec{u}_a)$$

Budget equation for any local variable ψ

Budget for any geometric volume V

$$\frac{\partial \int_V \sum_l (\rho_l \psi_l) dv}{\partial t} = - \int_S \sum_l (\rho_l \psi_l \vec{u}_l \cdot \vec{n}) ds + \int_V \sum_l \dot{S}_l dv$$

Local form of the budget equation

$$\frac{\partial (\rho \psi)}{\partial t} = -\text{div} \left[\sum_l (\rho_l \psi_l \vec{u}_l) \right] + \sum_l \dot{S}_l$$

Advection term

Barycentric advection

$$\rho \frac{\partial(\psi)}{\partial t} + \rho \vec{u} \cdot \text{grad}(\psi) = \underbrace{-\frac{\partial[\sum_l (\rho_l \psi_l \tilde{w}_l)]}{\partial z}}_{(+)} + \sum_l \dot{S}_l$$

with $\psi = \sum_l q_l \psi_l$ and $\sum_l (\rho_l \tilde{w}_l) = 0$

Alternative : Dry air advection (Bannon, 2002)

$$\rho_a \frac{\partial(\psi)}{\partial t} + \rho_a \vec{u}_a \cdot \text{grad}(\psi) = \underbrace{-\frac{\partial[\sum_l (\rho_l \psi_l \check{w}_l)]}{\partial z}}_{(+)} + \sum_l \dot{S}_l$$

with $\psi = \sum_l r_l \psi_l$ but $\sum_l (\rho_l \check{w}_l) \neq 0$

Turbulent / organised diffusive terms

Budget equation for any model scale variable

$$\begin{aligned}
 \frac{\partial(\overline{\rho\psi})}{\partial t} &= -\text{div}(\overline{\rho\psi\vec{u}}) - \text{div}(\overline{\rho\psi''\vec{u}''}) \\
 &\quad - \frac{\partial[\sum_l \overline{\rho\hat{q}_l\hat{\psi}_l\hat{w}_l}]}{\partial z} - \frac{\partial[\sum_l \overline{\hat{q}_l\rho\psi_l''\tilde{w}_l''}]}{\partial z} \\
 &\quad - \frac{\partial[\sum_l \overline{\psi_l\rho q_l''\tilde{w}_l''}]}{\partial z} - \frac{\partial[\sum_l \overline{\tilde{w}_l\rho q_l''\psi_l''}]}{\partial z} - \frac{\partial[\sum_l \overline{\rho q_l''\psi_l''\tilde{w}_l''}]}{\partial z} \\
 &\quad + \sum_l \bar{S}_l
 \end{aligned}$$

Simplified form

$$\begin{aligned}
 \bar{\rho} \frac{\partial(\hat{\psi})}{\partial t} + \underbrace{\overline{\rho\vec{u}} \cdot \text{grad}(\hat{\psi})}_{- \text{ advection}} &= - \underbrace{\text{div}(\overline{\rho\psi''\vec{u}''})}_{\text{ turbulent}} - \underbrace{\frac{\partial[\sum_l \overline{\rho\hat{q}_l\hat{\psi}_l\hat{w}_l}]}{\partial z}}_{\text{ organised}} + \sum_l \bar{S}_l
 \end{aligned}$$

Mass budget for species l

Mass of l variations in any volume V

$$\frac{\partial m_l}{\partial t} = - \int_S \rho_l \vec{u}_l \cdot \vec{n} dS + \int_V \dot{\rho}_l dv$$

with $m_l = \bar{\rho}_l V = \int_V \rho_l dv = \int_V \rho q_l dv$ and $\dot{\rho}_l$ the source/sink

Model scale equation for q_l

Eulerian form

$$\frac{\partial \bar{\rho} \hat{q}_l}{\partial t} = -\text{div}(\bar{\rho} \hat{q}_l \hat{\mathbf{u}}) - \frac{\partial (\bar{\rho} \hat{q}_l \hat{w}_l)}{\partial z} - \frac{\partial (\overline{\rho q_l'' w_l''''})}{\partial z} + \bar{\rho} \dot{q}_l$$

Lagrangian form

$$\bar{\rho} \frac{\widehat{D} \hat{q}_l}{Dt} = \bar{\rho} \left(\frac{\partial \hat{q}_l}{\partial t} + \hat{\mathbf{u}} \cdot \vec{\text{grad}}(\hat{q}_l) \right) = -\frac{\partial (\bar{\rho} \hat{q}_l \hat{w}_l)}{\partial z} - \frac{\partial (\overline{\rho q_l'' w_l''''})}{\partial z} + \bar{\rho} \dot{q}_l$$

Barycentric momentum budget

Variations of one component of the barycentric momentum for any volume V

$$\begin{aligned}
 \frac{\partial \left(\int_V (\sum_l \rho_l u_l^\alpha) dv \right)}{\partial t} &= - \int_S \left(\sum_l \rho_l u_l^\alpha \vec{u}_l \right) \cdot \vec{n} ds \\
 &+ \int_V \left(\sum_l \rho_l g^\alpha \right) dv \\
 &+ \int_V \left(\sum_l \rho_l [2\vec{\Omega} \wedge \vec{u}_l]^\alpha \right) dv \\
 &+ \int_S [\vec{\tau}_s \cdot \vec{n}]^\alpha ds
 \end{aligned}$$

The stress tensor

Hypothesis on the stress tensor

We suppose that $\vec{\tau}_s$ may be written as the sum of two tensors :

$$\vec{\tau}_s = -p \vec{\delta} + \vec{\sigma}$$

with p the total pressure of the gas and $\vec{\sigma}$ the viscous stress tensor (« molecular diffusion »).

Barycentric momentum budget

Variations of one component of the barycentric momentum for any volume V

$$\begin{aligned}
 \int_V \left[\frac{\partial(\rho u^\alpha)}{\partial t} \right] dv &= - \int_V \operatorname{div} \left(\sum_l \rho_l u_l^\alpha \vec{u}_l \right) dv \\
 &+ \int_V (\rho g^\alpha) dv \\
 &+ \int_V \left(\rho [2\vec{\Omega} \wedge \vec{u}]^\alpha \right) dv \\
 &- \int_V [\operatorname{grad}(\rho)]^\alpha dv + \int_V \operatorname{div}[\vec{\sigma}_s^\alpha] dv
 \end{aligned}$$

Barycentric zonal momentum equation at model scale

Eulerian budget

$$\frac{\partial(\overline{\rho\hat{u}})}{\partial t} = -\text{div}(\overline{\rho\hat{u}\hat{u}}) - \text{div}(\overline{\rho u''\vec{u}''}) + 2\overline{\rho}\Omega \sin(\varphi)\hat{v} - \frac{\partial\overline{p}}{\partial x} + \text{div}(\overline{\sigma_u})$$

« Lagrangian » form

$$\begin{aligned} \overline{\rho} \frac{D\hat{u}}{Dt} &= \overline{\rho} \left[\frac{\partial\hat{u}}{\partial t} + \hat{u} \cdot \text{grad}(\hat{u}) \right] \\ &= -\text{div}(\overline{\rho\vec{u}''u''}) + 2\overline{\rho}\Omega \sin(\varphi)\hat{v} - \frac{\partial\overline{p}}{\partial x} + \text{div}(\overline{\sigma_u}) \end{aligned}$$

Barycentric NH vertical momentum equation at model scale

« Lagrangian » form

$$\bar{\rho} \frac{\partial (\hat{w})}{\partial t} + \bar{\rho} \hat{u} \cdot \vec{\text{grad}}(\hat{w}) = -\text{div}(\overline{\rho w'' \vec{u}''}) - \frac{\partial (\sum_l \overline{\rho_l \tilde{w}_l^2})}{\partial z} - \bar{\rho} g - \frac{\partial \bar{p}}{\partial z} + \text{div}(\overline{\sigma_w})$$

Barycentric NH vertical momentum equation at model scale

The second term on the right hand side of the last equation may be decomposed in :

$$\begin{aligned}
 -\frac{\partial \left(\sum_l \overline{\rho_l \tilde{w}_l^2} \right)}{\partial z} &= -\frac{\partial \left(\sum_l \overline{\rho q_l \tilde{w}_l^2} \right)}{\partial z} \\
 &= -\frac{\partial \left(\sum_l \overline{\rho \hat{q}_l \hat{w}_l^2} \right)}{\partial z} \\
 &\quad - \frac{\partial \left(\sum_l \overline{\rho q_l'' \hat{w}_l^2} \right)}{\partial z} - 2 \frac{\partial \left(\sum_l \overline{\rho \hat{q}_l \hat{w}_l \tilde{w}_l''} \right)}{\partial z} \\
 &\quad - 2 \frac{\partial \left(\sum_l \overline{\rho q_l'' \hat{w}_l \tilde{w}_l''} \right)}{\partial z} - \frac{\partial \left(\sum_l \overline{\rho q_l'' (\tilde{w}_l'')^2} \right)}{\partial z}
 \end{aligned}$$

Barycentric NH vertical momentum budget

We keep only the first term of this development. The average NH equation for the vertical velocity is then finally :

$$\begin{aligned} \bar{\rho} \frac{\partial(\widehat{w})}{\partial t} + \bar{\rho} \widehat{u} \cdot \vec{\text{grad}}(\widehat{w}) &= -\text{div}(\overline{\rho w'' \vec{u}''}) \\ &= -\frac{\partial \left(\sum_l \bar{\rho} \widehat{q}_l \widehat{w}^2_l \right)}{\partial z} \\ &\quad - \bar{\rho} g \\ &\quad - \frac{\partial \bar{p}}{\partial z} + \text{div}(\overline{\sigma_w}) \end{aligned}$$

Total energy budget

Method

The classical method to deduce the thermodynamic equation is to subtract the equation for the kinetic energy from the equation for the total energy (kinetic energy + internal energy).

In practice

- do this operation at the local scale
- apply the average operator on the resulting thermodynamic equation
- if we neglect some non linear terms, the exact form of the mean thermodynamics equation may depend on the form of the local equation to which the averaging is applied.

Hydrostatic thermodynamic equations at model scale

Neglecting all the term with a perturbation of c_p or a perturbation of \tilde{w}_k and the presso-correlations

$$\begin{aligned}
 \frac{\partial \bar{\rho} \widehat{c}_p \widehat{T}}{\partial t} + \text{div}(\bar{\rho} \widehat{c}_p \widehat{T} \widehat{\vec{u}}) &= \frac{\partial \bar{\rho}}{\partial t} + \widehat{\vec{u}} \cdot \text{grad} \bar{\rho} \\
 &+ \text{div}(\widehat{c}_p \overline{\rho T'' \vec{u}''}) \\
 &- \frac{\partial \left[\sum_k \left(\bar{\rho} c_{p_k} \widehat{q}_k \widehat{T} \widehat{w}_k \right) \right]}{\partial z} \\
 &+ \bar{\epsilon} + \text{div}(\overline{\vec{J}_Q}) \\
 &+ L_v(T=0) \bar{\rho}_l + L_i(T=0) \bar{\rho}_i
 \end{aligned}$$

Hydrostatic temperature equation at model scale

$$\begin{aligned}
 \bar{\rho} \widehat{c}_p \frac{\widehat{D}\widehat{T}}{Dt} &= \frac{\widehat{D}\bar{p}}{Dt} \\
 &+ \text{div}(\widehat{c}_p \overline{\rho T'' \vec{u}''}) \\
 &- \sum_k \left(\bar{\rho}_k \widehat{w}_k \frac{\partial c_{pk} \widehat{T}}{\partial z} \right) \\
 &+ \bar{\epsilon} + \text{div}(\overline{\vec{J}_Q}) \\
 &+ L_v(T) \overline{\dot{\rho}_l} + L_i(T) \overline{\dot{\rho}_i}
 \end{aligned}$$

NH total energy budget at local scale

$$\rho \left[\frac{\partial (e_i + \tilde{e}_c)}{\partial t} + \vec{u} \cdot \vec{\text{grad}}(e_i + \tilde{e}_c) \right] = - \frac{\partial (\sum_k (\rho_k e_{i_k} + p_k) \tilde{w}_k)}{\partial z} - \rho \tilde{e}_c \frac{\partial (w)}{\partial z} - p \text{div}(\vec{u}) + \epsilon + \text{div}(\vec{J}_Q)$$

Practical applications for Arome

Tendency and diagnostic (budget) interface

Because of the « finite » falling velocity of the precipitation, the current budget equations used in the Arpege/Aladin physics to compute the physical tendencies from fluxes and in the diagnostics (DDH) is not valid. A more generalised set of equations/interface as to be coded (B. Catry et al) and a nice set of fluxes have to be recovered from the microphysic processes (T. Kovavic et al).

Barycentric departure fluxes

The « new » terms (« barycentric departure fluxes ») in the equations should be coded and analysed (computational cost compared to order of magnitude).