Mesoscale Atmospheric Predictability

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> http://www2.uibk.ac.at/meteo http://www.zamg.ac.at/workshop2004/

Outline

- **1 Predictability:** error growth
- **2 Global Models: doubling times**
- **3 Singular Vectors:** assessing growth
- **4 Mesoscale Studies:** moist physics
- **5 Ensemble Prediction:** sampling
- **6** Conclusions







T+36; 02/06/2004/00

EC00 - EC 12 12 UTC Run; 31MAY2004 +36 00 UTC Run; 01JUN2004 +24

+24 – T+36

02/06/2004/00 isoline spacing; geopotential height 4 [10m] 24 22 18 16 14 12 10 9 6 5 3 2 0

-2 -3 -4 -5

-6 -8 -9 -10 -1: -1--16

-11 -21 -21

-2. -26

EC00 - EC 12

ECMWF FORECAST DIFFERENCE: geopotential height [10m] at 500 hPa. Thu 03JUN2004 00 UTC

12 UTC Run: 31MAY2004 +48 00 UTC Run: 01JUN2004 +36

F+48 – T+60 03/06/2004/06

12 UTC Run: 31MAY2004 +60 00 UTC Run: 01JUN2004 +48

isoline spacing; geopotential height 4 [10m]



ECMWF FORECAST DIFFERENCE: geopotential height [10m] at 500 hPa. Wed 02JUN2004 00 UTC



ECMWF FORECAST DIFFERENCE: geopotential height [10m] at 500 hPa, Tue 01JUN2004 12 UTC

ECMWF FORECAST DIFFERENCE: geopotential height [10m] at 500 hPa. Wed 02JUN2004 12 UTC

14 12 10

-2 -3

-22 -24 -26



rms of difference between forecasts verifying at same time, but with initial states lagging by 24 hours (48 hours, ...)

 \rightarrow growth of 1-day, 2-day, ... forecast errors

forecast differences grow slower than difference between model and analysis (= forecast error)

Figure 1: Error growth curves from Lorenz (1982).

 intrinsic error growth
 chaotic: to extent to which model and atmosphere correspond

Description: Error growth model Lorenz (1982)

- E^* rms saturation error, E rms error
- doubling time $\tau_d = \alpha^{-1} \ln 2$

$$\frac{1}{E}\frac{dE}{dt} = \alpha \frac{E^* - E}{E^*} \tag{1}$$

with solution

$$E(t) = \frac{E^* \left(1 + \tanh\left[\frac{\alpha}{2} \left(t - t_0\right)\right]\right)}{\frac{E^*}{E_0} \left(1 - \tanh\left[\frac{\alpha}{2} \left(t - t_0\right)\right]\right) + 2 \tanh\left[\frac{\alpha}{2} \left(t - t_0\right)\right]}$$
(2)

Cutting initial state error in half → adding one doubling time in range of predictability (in exponential regime)

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$$E^* = \sqrt{2}\sigma_{clim}$$

solution with:



R.m.s. errors and differences between successive forecasts Northern hemisphere 500hPa height Winter



A. Simmons, ECMWF

amplification of 1-day forecast error, 1.5 days

nonlinearity of dynamics

and

 \rightarrow

instability with respect to small perturbations

sensitive dependence on present condition chaos

irregularity and nonperiodicity

unpredictability and error growth









GEOPOTENTIAL HEIGHT SPECTRA 500 mb T42 T106 T63 (a) (b) (C) 10000 10000 10000 100 100 100 1 0.5 0.01 0.01 0.01 100 10 40 10 40 100 10 40 100 1

error growth to due resolution differences (against T170):

D+1 error T42 = 10 x D+1 error T63 = 10 x D+1 error T106



even at T42 the D+1 truncation error growth has not exceeded D+1 IC T106 growth

T106 truncation error growth is one order of magnitude smaller than D+1 T106 IC error growth

need IC/10 before going beyond T106

[IC analysis error growth exponential]

> Tribbia Baumhefner 2004



Singular Vectors

Maximize the L2 norm: $N = \mathbf{y}^{\dagger} \mathbf{N} \mathbf{y}^{\dagger}$ Given the TLM: $\mathbf{y}' = \mathbf{M}\mathbf{x}'$ Constraint: $1 = C = \mathbf{x}^{\prime \dagger} \mathbf{C} \mathbf{x}^{\prime}$ Solution: $x' = C^{-\frac{1}{2}}z$ $\lambda^2 \mathbf{z} = \mathbf{C}^{-\frac{1}{2}} \mathbf{M}^{\dagger} \mathbf{N} \mathbf{M} \mathbf{C}^{-\frac{1}{2}} \mathbf{z}$

R.M. Errico

SVs / HSVs -> fastest growing directions: account for in initial condition stability of the flow



psi´ at 500 hPa Optimized TL error growth

b1br time series of psi t/h= 12.0 level 2 mi/ma/rms/x/std -3.8603E+00 2.3934E+00 2.9200E-01 -7.4994E-03 2.9191E-01



French storm

b1br time series of psi t/h= 24.0 level 2 mi/ma/rms/x/std -7.6639E+00 5.8000E+00 6.1703E-01 2.7094E-04 6.1703E-01



data assimilation, stability, error dynamics

Atmospheric Predictability and Data Assimilation, 9 March 2004

0-118







FIG. 5. First TE-norm SV for case 1 in terms of T at (a) $\sigma = 0.35$ (approximately 350 hPa) and (b) $\sigma = 0.65$ (approximately 650 hPa). Units and CIs: (a) 10^{-4} K, 0.01 K; (b) 10^{-3} K, 0.02 K. Zero contours are suppressed.

tau_d = 4.1 h

Ehrendorfer/Errico 1995

MAMS - DRY

TE-Norm

3480

Mesoscale Adjoint Modeling System MAMS2

PE with water vapor (B grid) Bulk PBL (Deardorff) Stability-dependent vertical diffusion (CCM3) RAS scheme (Moorthi and Suarez) Stable-layer precipitation Dx=80 km 20-level configuration (d sigma=0.05) Relaxation to lateral boundary condition

12-hour optimization for SVs4 synoptic cases

moist TLM (Errico and Raeder 1999 QJ)

Energy Profiles and Wavenumber Spectra: HSVs and TESVs Northern Hemisphere 25 SVs Autumn 1999



Jan Barkmeijer, ECMWF



Figure 1: Growth of errors initially confined to smallest scales, according to a theoretical model (taken from a paper by E. Lorenz presented in AIP Conf. Proceedings #106). Horizontal scales on bottom; full atmospheric motion spectrum = upper curve.

Lo<mark>renz 1969</mark>

Tribbia/Baumhefner 2004

errors in small scales propagate upscale ... in spectral space

small-scale errors grow and ... contaminate ... larger scale

Adjoint Sensitivity Analysis The Problem

Given a differentiable scalar measure $J = J(\mathbf{y})$ and a model $\mathbf{y} = \mathcal{M}(\mathbf{x})$ grad_x J = M^T grad_y J determine $\partial J/\partial x_i$ such that $J' = \sum_i \frac{\partial J}{\partial x_i} x'_i$ approximates $\Delta J = J(\mathbf{x} + \mathbf{x}') - J(\mathbf{x})$ The solution is: $rac{\partial J}{\partial x_i} = \sum_i rac{\partial y_j}{\partial x_i} rac{\partial J}{\partial y_j}$ Μ Contrast with: $J' = \sum_i \frac{\partial J}{\partial y_i} y'_i$ $y'_i = \sum_j \frac{\partial y_i}{\partial x_j} x'_j$

R.M. Errico





Contour interval 0.02 Pa/m M=0.1 Pa/m

4 MOIST PHYSICS

Errico et al. 2004 QJ

initial- and final-time norms

E_m -> E

E -> E

V_d -> E

V_d -> P

V_m -> E

V_m -> P

Norms Considered

Energy Norm:

Ρ

V m

 $\mathbf{E} \qquad E = \frac{1}{N_w} \sum_{i,j,k} \Delta \sigma_k \left(u_{i,j,k}^{\prime 2} + v_{i,j,k}^{\prime 2} \right) + \frac{C_p}{T_r N_t} \sum_{i,j,k} \Delta \sigma_k T_{i,j,k}^{\prime 2} + \frac{RT_r}{p_{sr}^{2} N_t} \sum_{i,j} p_{s\ i,j}^{\prime 2} \tag{1}$

Moist Energy Norm (dry fields zero):

 $\mathbf{E}_{m} = \frac{L^{2}}{C_{p}T_{r}N_{t}} \sum_{i,j,k} \Delta \sigma_{k} q_{i,j,k}^{\prime 2}$ (2)

Precip. Rate Norm (used only as end-time norm; non-convective + convective precip.):

$$P = \frac{1}{N_t} \sum_{i,j} R_{t\ i,j}^{\prime 2}$$
(3)

Dry and Moist Variance–weighted norm (penalize large q high up):

$$\mathbf{V}_{d} \quad V_{d} = \frac{1}{N_{w}} \sum_{i,j,k} \Delta \sigma_{k} \left(\frac{u_{i,j,k}^{\prime 2}}{V_{u\ k}} + \frac{v_{i,j,k}^{\prime 2}}{V_{v\ k}} \right) + \frac{1}{N_{t}} \sum_{i,j,k} \Delta \sigma_{k} \frac{T_{i,j,k}^{\prime 2}}{V_{T\ k}} + \frac{1}{N_{t}} \sum_{i,j} \frac{p_{s\ i,j}^{\prime 2}}{V_{p}}$$
(4)

$$V_m = \frac{1}{N_t} \sum_{i,j,k} \frac{q_{i,j,k}^{\prime 2}}{V_q \ k} \Delta \sigma_k \tag{5}$$

A larger value of E can be produced with an initial

constraint V_m=1 compared with V_d=1.

(hypothetical norm comparison: "larger E with E_m=1 compared with V_d=1")

MAMS - MOIST





Perturbations in Different Fields Can Produce the Same Result

12-hour v TLM forecasts

Initial u, v, T, ps Perturbation

Initial q Perturbation



Errico et al. QJRMS 2004

H=c_p T + L q condensational heating

summarizing comments on moist-norm SV-study:

- moisture perturbations alone may achieve larger
 E than dry perturbations
- given same initial constraint, similar structures can be optimal for maximizing E and P in most cases however: structures are different
- dry-only and moist-only SVs may lead to nearly identical final-time fields (inferred dependence on H);
 q converts to T (diabatic heating) through nonconvective precipitation

[- nonlinear relevance: TLD vs NLD may match closely (2 g/kg)]

[- sensitivity of non-convective precipitation not universally dominant]

5 Ensemble Prediction

- generate perturbations from (partial) knowledge of analysis error covariance P[^]a
- methodology on the basis of SV
- "SV-based sampling technique"

Uncertainty Prediction: Hessian SVs

The HSVs Z_0 solving the eigenvector problem:

$$\mathsf{M}^{\mathrm{T}}\mathsf{C}^{\mathrm{T}}\mathsf{C}\mathsf{M}\mathsf{Z}_{0} = (\mathsf{P}^{\mathsf{a}})^{-1}\mathsf{Z}_{0}\Lambda \qquad \text{ s.t. } \mathsf{Z}_{0}^{\mathrm{T}}(\mathsf{P}^{\mathsf{a}})^{-1}\mathsf{Z}_{0} = \mathsf{I}$$

are, when time–evolved, eigenvectors of P^f, because:

$$\Big(C \underbrace{\mathsf{M}\mathsf{P}^{\mathsf{a}}}_{\equiv \mathsf{P}^{\mathsf{f}}} \mathbf{M}^{\mathrm{T}} \underbrace{\mathsf{C}^{\mathrm{T}} \underbrace{\mathsf{C}\mathsf{M}\mathsf{Z}_{0}}_{\equiv \mathsf{Z}_{\mathsf{t}}}}_{\equiv \mathsf{Z}_{\mathsf{t}}} = \Big(\mathsf{C}\mathsf{M}\mathsf{P}^{\mathsf{a}} \Big) (\mathsf{P}^{\mathsf{a}})^{-1} \mathsf{Z}_{0} \Lambda \qquad \rightarrow$$

$$\left(CP^{f}C^{\mathrm{T}}\right)Z_{t}=Z_{t}\Lambda$$

(5.0.2)

The evolved HSVs Z_t are the eigenvectors of CP^fC^T – which is the forecast error covariance in the "final-time norm" C. Note the final time orthogonality relationship:

Uncertainty Prediction: The SV–Decomposition of P^a

• Because the initial time SVs satisfy (5.0.1), it is true that P^a can be written as:

$$\mathsf{P}^{\mathsf{a}} = \mathsf{Z}_{\mathsf{0}}\mathsf{Z}_{\mathsf{0}}^{\mathrm{T}} \tag{5.0.4}$$

This is a special square root for P^a (different from eigendecomposition and also not lower-triangular) \rightarrow the **SV-decomposition of** P^a

• Under linear dynamics this SV decomposition becomes the eigendecomposition of the forecast error covariance matrix, because (5.0.5) is the same as (5.0.2) together with (5.0.3):

$$\left(\mathsf{CM}\right)\mathsf{P}^{\mathsf{a}}\left(\mathsf{CM}\right)^{\mathrm{T}} = \left(\mathsf{CM}\right)\mathsf{Z}_{\mathsf{0}}\mathsf{Z}_{\mathsf{0}}^{\mathrm{T}}\left(\mathsf{CM}\right)^{\mathrm{T}} \rightarrow$$

$$CP^{f}C^{T} = Z_{t}Z_{t}^{T}$$
(5.0.5)

• SV-decomposition implemented at ECMWF for generation of initial-time perturbations in the Ensemble-Prediction-System (only partly operational)

Multinormal Sampling Based on SV–Decomposition of P^a

• Transforming random variables

$$\mathbf{q} \sim \mathcal{N}(0, \mathbf{I}) \quad \Rightarrow \quad \mathbf{x} = \mathbf{x}_0^c + \mathbf{V}^{1/2} \mathbf{q} \quad \rightarrow \quad \mathbf{x} \sim \mathcal{N}(\mathbf{x}_0^c, \mathbf{V}) \quad (5.0.6)$$

Use SV-decomposition of P^a (possibly truncated to N SVs) in (5.0.5) – to describe square-root of P^a – in process of generating initial-time perturbed states x:

$$(\mathsf{P}^a)^{1/2} = \mathsf{Z}_0^{(N)} \tag{5.0.7}$$

$$\mathbf{x}_{i} = \mathbf{x}_{0}^{c} + \mathsf{Z}_{0}^{(N)}\mathbf{q}_{i} \qquad i = 1, 2, ..., M \quad \Rightarrow \qquad \mathbf{x} \sim \mathcal{N}\left(\mathbf{x}_{0}^{c}, (\mathsf{P}^{\mathsf{a}})^{(N)}\right) \qquad (5.0.8)$$

- Generating perturbations consistent with P^a knowledge based on N SVs
- Assumes normally distributed analysis errors; non eigendecomp. \rightarrow eigendecomp.
- Taking SV properties into nonlinear regime
- Strong similarity to operational *rotation* at ECMWF
- free parameters: N and M



R. M. ERRICO ET AL.

Case no.	Case label	Physics	Norm	N	ĩ	L	N.	22	12	Sum
103.00	1114 -14	~ ~ J ~ · · · ·				^C	*' g	(*1	(*)e	
1	W1	dry	Е	79354	1000	406	<u></u>	54.9	1.53	1552.3
2	W1	wet	\mathbf{E}	79354	600	257		322.0	2.23	2387.7
3	W1	dry	R	24940	600	265	270	38.1	1.01	791.6
4	W1	dry	TR	4830	390	180	169	28.2	0.95	504.1
5	W1	wet	TR	4830	750	416	175	39.5	0.35	762,2
6	W2	dry	TR	4830	400	191	171	19.6	0.90	521.8
7	W2	wet	TR	4830	400	197	178	59.2	0.90	633.4
8	S 1	dry	E	65080	600	258		64.9	1.53	1117.3
9	S 1	wet	Е	65080	600	276		2547.9	1.55	6627.4
10	S1	dry	TR	3969	400	213	104	20.4	0.44	381.9
11	S1	wet	TR	3969	400	211	115	368.2	0.47	1126.3
12	S 2	dry	TR	3969	400	196	124	11.1	0.62	354.7
13	S 2	wet	TR	3969	400	206	134	81.1	0.61	659.2

Table 1. Description of experiments and some results

N is the size of the (sub-) space measured by the norm. I is the number of iterations of the Lanczos algorithm performed. I_c is the number of converged λ^2 . N_g is the number of $\lambda_k > 1$. Sum is $\sum_{k=1}^{I_c} \lambda_k^2$.

169 SVs growing out of 4830 (dry balanced norm)

i.e. 3.5% of phase space



TD and TM curves: 169 (dry) and 175 (wet) growing SVs

Fig. 3. Converged λ_k for the five sets of SVs determined for case W1. *E*, *R*, and *T* denote results for the energy, rotational mode, and truncated rotational mode norms, respectively. M and D denote results for moist and dry TLM, respectively. A line for which $\lambda_k^2 \propto k^{-2/3}$ is also indicated.



Figure 8.7: Day–4 geopotential height correlations at 500hPa obtained from ECMWF operational forecast starting from 2001121912. Also shown is Z500 height field from control forecast (black contours).

Wednesday 19 December 2001 12UTC ECMWF_EPS Control Forecast t+96 VT: Sunday 23 December 2001 12UTC 500hPa geopotential height Wednesday 19 December 2001 12UTC ECMWF_EPS Perturbed Forecast t+96 VT: Sunday 23 December 2001 12UTC 500hPa "geopotential height - Ensemble member number 50 of 51



Figure 8.8: as Fig. 8.7, but for sampling experiment M = 50/N = 25 starting from 2001121912.

height correlations 500 hPa derived from ensemble Integrations (D+4)



Wednesday 19 December 2001 12UTC ECMWF EPS Control Forecast t+96 VT: Sunday 23 December 2001 12UTC 500hPa geopotential height Wednesday 19 December 2001 12UTC ECMWF EPS Perturbed Forecast t+96 VT: Sunday 23 December 2001 12UTC 500hPa "geopotential height - Ensemble member number 100 of 101



Figure 8.9: as Fig. 8.7, but for sampling experiment M = 100/N = 50 starting from 2001121912.

Summary

Intrinsic Error Growth

limited predictability (nonlinearity) presence of analysis error

Predictability

rapid doubling of analysis error account for fastest error growth: SV dynamics importance of lower troposphere insight into growth mechanisms initial moisture perturbations

Ensemble Prediction

generation of perturbations: sampling SV relation to analysis error: nonmodal IC growth