

http://www.umr-cnrm.fr/aladin/



Period 2010-2015

Issue Coodrination during 2015-2020

Code engineering: ACNA

Management of the cycles

Schools of thought on physics:

Code Architect

to parameterize or not to parameterize DC?

Data assimilation:

A solution for all?

DASKIT

































Physics (CA)

The Code Architect shall technically assist the ALADIN PM in supervising the definition of the ALADIN System, see, ARTICLE 5, Paragraph 43

This includes the following specific tasks; the Code Architect (CA)

- will finalize the physics-dynamics action;
- will document the scientific consistency between different physics packages and the dynamics;
- propose technical solutions to implement new pieces of code in the model code, consistent
 with the common numerical framework (including the physics-dynamics interface and the
 constraints from the time step organization);
- will execute a 5-year engineering program with the aim to define the ALADIN System, according to a road map agreed with the ALADIN PM and PAC;
- will monitor the definition of the Canonical Model Configurations.

The CA will de facto be part of CSSI and will work in close collaboration with the ACNA and the chair of CSSI.

The ALADIN PM regularly reports about the activity of the CA to PAC.



























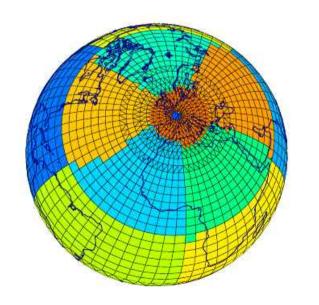


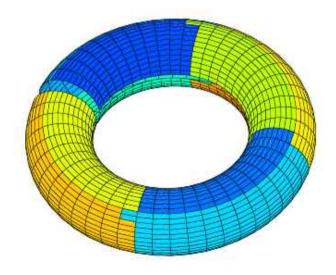


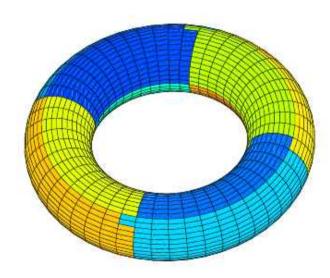


Addressing future evolutions of software infrastructure

- Adopt the notion of "separation of concerns": low level code to the local computing platform are not visible to the high-level scientific developer, thus separating the scientific concerns from the computing ones.
- Strengthen the collaboration with ECMWF (shared code)
- Work already started on Atlas to include LAM geometry
- Need to increase knowledge/efforts on DSL and Claw





























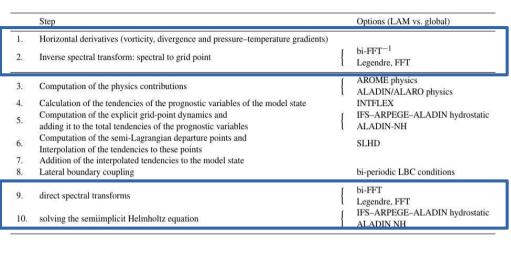


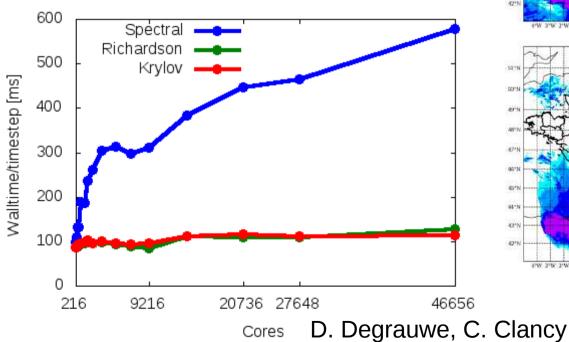


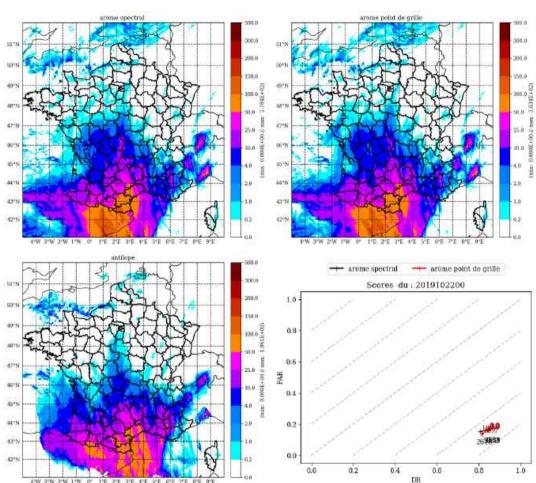




Gridpoint solver







T. Burgot, L. Auger



































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RESEARCH ARTICLE



A non-spectral Helmholtz solver for numerical weather prediction models with a mass-based vertical coordinate

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Abstract

Although semi-implicit semi-Lagrangian spectral atmospheric models have been very successful for decades, they are believed to face big challenges in the longer term. Foremost, the spectral method relies heavily on data-rich global communications, which may become problematic on future massively parallel machines. This paper investigates how the Helmholtz problem, as it arises in the dynamical core of a semi-implicit non-hydrostatic numerical weather prediction model with a mass-based vertical coordinate and a constant-coefficient reference state, can be solved efficiently without relying on spectral transforms, by using a multigrid-preconditioned iterative solver instead. In the particular case of a limited-area geometry, the convergence rate of this iterative solver can be determined a priori, which allows us to predict the required number of iterations. This knowledge is especially valuable for an atmospheric model that is used for operational weather forecasting, because it guarantees that the model runtime stays constant from one forecast to another. The a priori knowledge of the convergence rate also allows us to choose the parameters of the multigrid preconditioner optimally. Weak scalability experiments show the superior scalability of this solver with respect to a spectral solver.

KEYWORDS

Helmholtz problem, Krylov solver, scalability, semi-implicit timestepping, spectral methods





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Physics-dynamics interface

Geosci. Model Dev., 9, 2129–2142, 2016 www.geosci-model-dev.net/9/2129/2016/ doi:10.5194/gmd-9-2129-2016 © Author(s) 2016. CC Attribution 3.0 License.





Generalization and application of the flux-conservative thermodynamic equations in the AROME model of the ALADIN system

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The ALADIN System and its canonical model configurations AROME CY41T1 and ALARO CY40T1

Piet Termonia^{1,2}, Claude Fischer³, Eric Bazile³, François Bouyssel³, Radmila Brožková⁴, Pierre Bénard³, Bogdan Bochenek⁵, Daan Degrauwe^{1,2}, Mariá Derková⁶, Ryad El Khatib³, Rafiq Hamdi¹, Ján Mašek⁴, Patricia Pottier³, Neva Pristov⁷, Yann Seity³, Petra Smolíková⁴, Oldřich Španiel⁶, Martina Tudor⁸, Yong Wang⁹, Christoph Wittmann⁹, and Alain Joly³

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Configurations.

CA deliverables

CA action (see ToR)	Deliverables	Link to future Strategy				
physics-dynamics action	The flexible physics-dynamics interface (CPTEND_FLEX) was implemented in the code (Degrauwe et al. 2016)	The physics Area: the physics AL will deliver an analysis document on the convergence of the physics packages in 2023.				
document the scientific consistency between different physics packages and the dynamics	An analysis of the APLPAR and APL_AROME routines has been carried out, with focus on TOUCANS					
propose technical solutions to implement new pieces of code in the model code, consistent with the common numerical framework (including the physics-dynamics interface and the constraints from the time step organization)	 ACRANEB2 in AROME (done before the appointment of the CA) SURFEX in ALARO a new gridpoint solver consistent with the time-step of the ALADIN System (Degrauwe et al. 2020) development of the Atlas library for LAM configurations (Müller et al. 2019) 	 The Transversal area on future evolution of software infrastructure: continue the work on Atlas, extend the effort to DSL and Claw. The physics Area: the physics AL will deliver an analysis document on the convergence of the physics packages in 2023. 				
will execute a 5-year engineering program with the aim to define the ALADIN System, according to a road map agreed with the ALADIN PM and PAC;	The ALADIN System has been documented in the paper Termonia et al. (2018).					
will monitor the definition of the Canonical Model	Development of mittrailette tests of the HARMONIE-AROME configuration	The objectives of the System Area : specifically, the goal to <i>Develop a more distributed, efficient and continuous process</i>				

for the integration and validation of new



DasKIT: see Newsletter 15

ALADIN-HIRLAM NL 15, June 2020

M. Monteiro et al.

The DAsKIT programme: status and plans

Maria Monteiro, Ouali Aitmeziane, Haythem Belghrissi, Andrey Bogatchev, Yelis Cengiz, Alex Deckmyn, Idir Dehmous, Fatima Hdidou, Wafa Khalfaoui, Marcin Kolonko, João Rio, Zahra Sahlaoui, Meral Sezer, Malgorzata Szczęch-Gajewska, Boryana Tsenova



























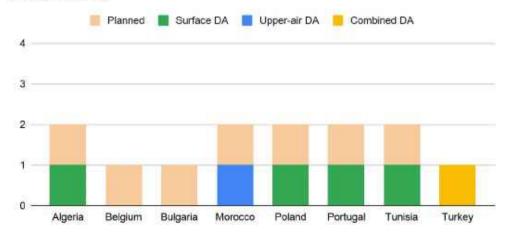




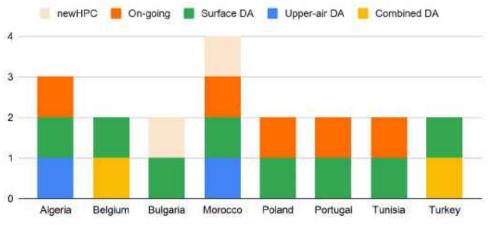
DAsKIT

Operational		RUN OVER															
con	iligurations	Algeria 8	Belgium (6	Gulgaria	Moreces	Poland	Portugal	Tunisia	Turkey	Austria	Croatia	Czech Rep	Hungary	Romania	Slovaka	Slovenia	France
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	Belgium		ALARO 4														
	Bulgaria			ALADIN 7													
	Morocco	ALADIN 18	ALADIN 18	ALADIN 18	AROME 2.5		ALADIN 10	ALADIN 18	NLADIN								
	Poland		ALARO 4	ALARO 4		AROME 2.5				AROME 2.5	ALARD 4	AROME 2.5	AROME 2.5	ALARO 4	AROME 2.5	AROME 2.5	
RUN BY	Portugal						AROME 2.5										
	Tunisia							ALADIN 12									
	Turkey			AROME 25					AROME 2.5		ALARO 4.5			ALARO 45		ALARO 4.5	
	Austria		ALARO 5							AROME 2.5	AROME 2.5	AROME 2.5	AROME 2.5		AROME 2.5	AROME 2.5	
	Croatia									ALARO 8	ALARO 2	ALARO 8	ALARDB		ALARO 8	ALARO 2	
	Czech Rep		ALARO 4.7	ALARD 4.7		ALARO 4.7				ALARO 47	ALARO 4.7	ALARO 47	ALARO 4.7	ALARO 4.7	ALARO 4.7	ALARO 4.7	
	Hungary		ALARO B	ALARO 8		ALARO 8				ALARO B	ALARO 8	ALARO 8	AROME 2.5	ALARO 8	AROME 2.5	AROME 2.5	
	Romania			ALARO 6.5									ALARO 6.5	ALARO 6.5	ALARO ES		4
	Słovakia		ALARD 9	ALARO 9		ALARO 9				ALARO 9	ALARO 9	ALARO 9	ALARD 9	ALARO 9	ALARO 9	ALARO 9	
	Slovenia		ALARO 4.4							ALARO 4.4	ALARO 4.4	ALARO 4.4	ALARO 4.4		ALARO 4.4	ALARO 4.4	
	France		AROME LD							T							AROME





Combined DA, Upper-air DA, Surface DA, On-going and newHPC - START 2020



Start 2018 Start 2020



Questions?



























