

LACE operational applications ALADIN-LAEF and OPLACE

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ZAMG



- meso-scale ensemble system ALADIN-LAEF
- based on the limited area model ALADIN
- developed in frame of RC LACE cooperation,
- focusing on short range probabilistic forecast
- profiting from advanced multi-scale ALARO physics.
- provide forecast on daily basis for the national weather services of RC LACE partners
- applied to hydrology, energy industry and even in the nowcasting.



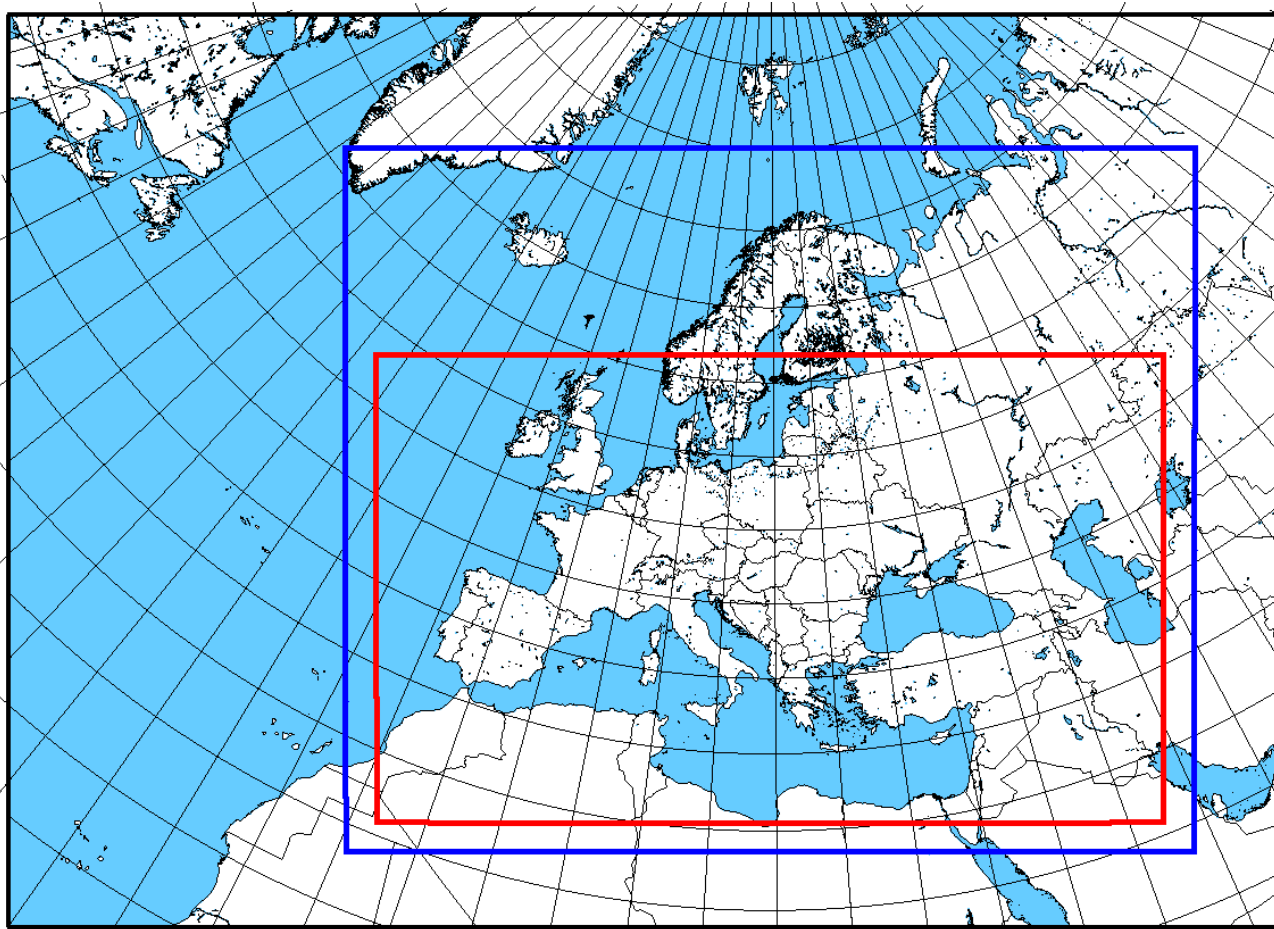
ZAMG



- operational in 2011, horizontal resolution of 18 km and 37 vertical levels, running in ECMWF.
- in 2013 the first substantial upgrade:
 - the increase of horizontal and vertical resolutions to 11 km and 45 vertical levels,
 - larger computational domain and
 - new ensemble of surface data assimilations involving perturbed screen-level conventional observations.
- now going towards 5 km / 60 levels and implementing several other upgrades.

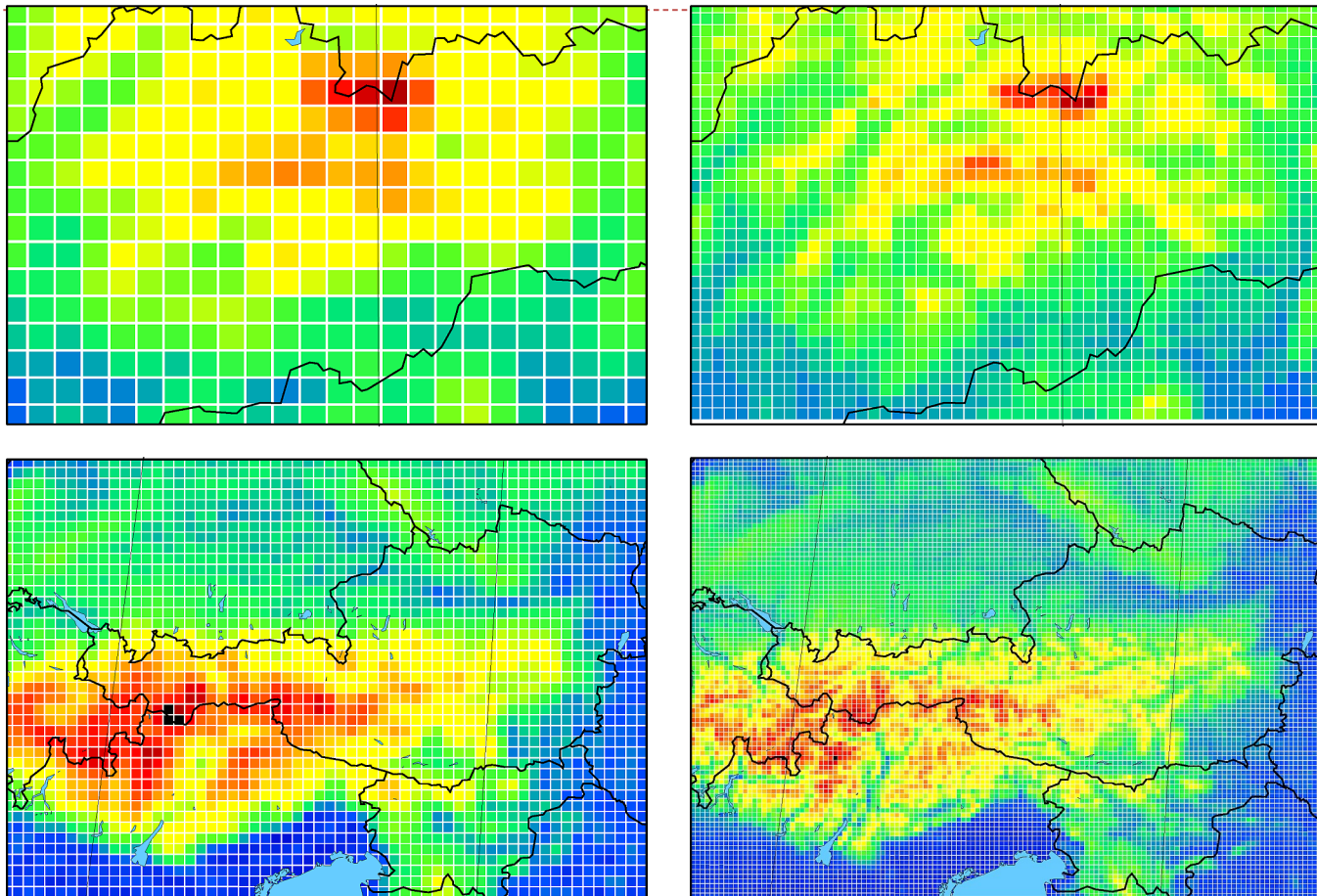


Computational domains



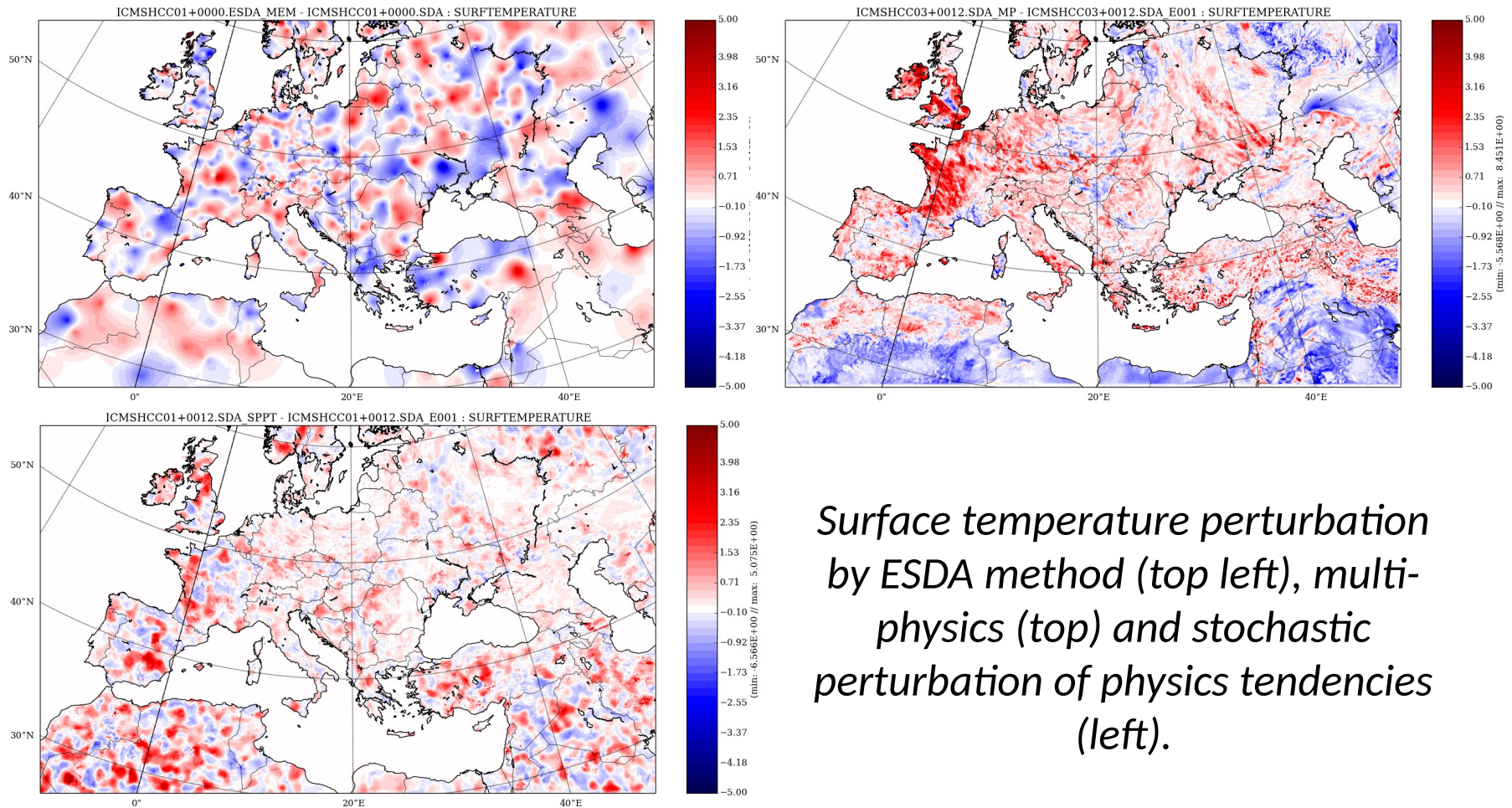
Current ALADIN-LAEF domain (blue) and upcoming domain after upgrade to 5 km horizontal resolution (red).

Model topography



Model orography for current 11 km grid (left) and new 5 km resolution (right). Tatra mountains in northern part of Slovakia (first row) and Austrian Alps (second row).

Surface temperature perturbations

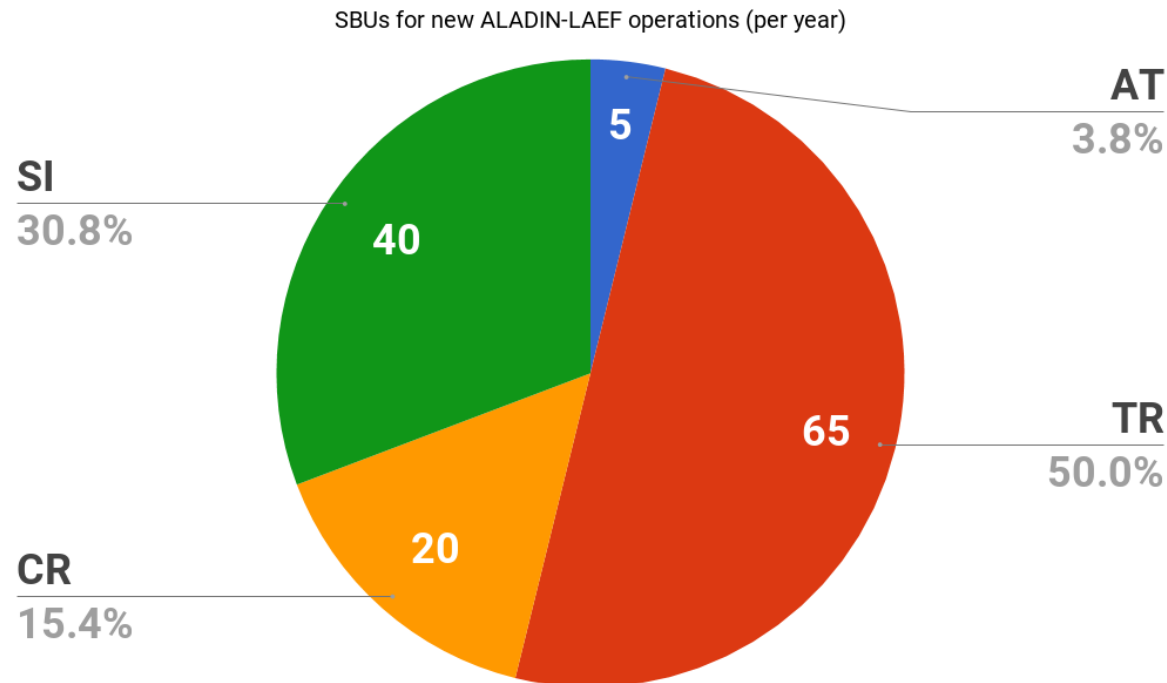


ALADIN-LAEF system specifications for current and new version

<u>ALADIN-LAEF</u>	current	new
Code version	cy36t1	cy40t1
Horizontal resolution	10,9 km	4,8 km
Vertical levels	45	60
Number of grid points	500x600	750x1250
Grid	quadratic	linear
Time step	450 s	180 s
Forecast length	72 h (00/12 UTC)	72 h (00/12 UTC)
Members	16+1	16+1
IC perturbation	ESDA [surface], breeding-blending [upper-air]	ESDA [surface], blending (Phase I) / ENS BlendVar (Phase II) [upper-air]
Model perturbation	ALARO-0 multi-physics	ALARO-1 multi-physics + surface SPPT
LBC perturbation	ECMWF ENS	ECMWF ENS
SBUUs consumed per year	~10 mil	~120 mil



SBU costs division between Austria, Turkey, Slovenia and Croatia



The scripting system of new ALADIN-LAEF Phase I configuration

ESDA

Slide 1

$$\Delta T_s = \Delta T_{2m}$$

$$\Delta T_p = \frac{1}{2\pi} \Delta T_{2m}$$

$$\Delta W_s = \alpha_s^T \Delta T_{2m} + \alpha_s^H \Delta H_{2m}$$

$$\Delta W_p = \alpha_p^T \Delta T_{2m} + \alpha_p^H \Delta H_{2m}$$

BLENDING

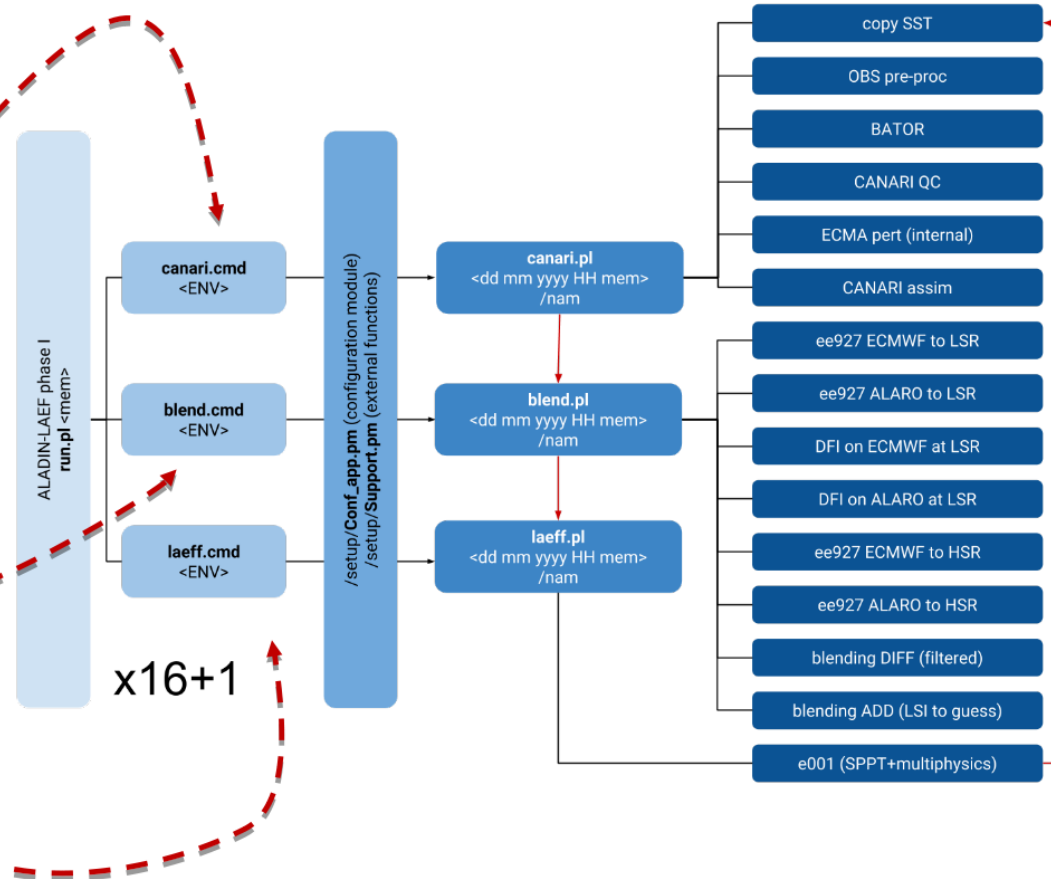
$$IC_{blend}^n = a_{breed}^n + \{ \overline{(a_{sv}^n)_{trunc}} - \overline{(a_{breed}^n)_{trunc}} \}$$

$$IC_{blend}^n = LS^n + a_{breed}^n$$

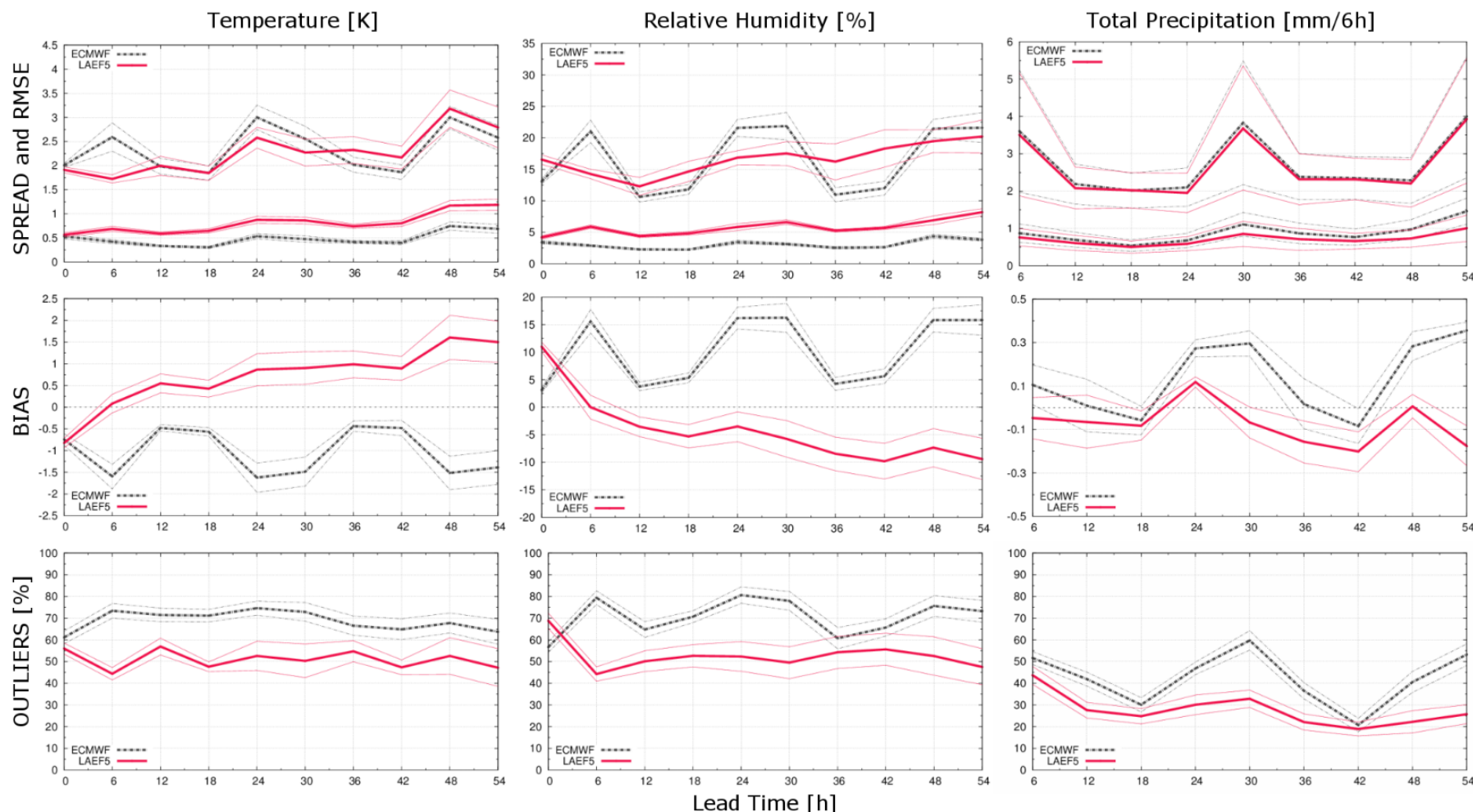
SPPT+MP

$$\frac{\partial e_j}{\partial t} = A(e_j, t) + P'(e_j, t)$$

$$P'_j(e_j, t) = (1 + r_j(\lambda, \varphi, t)_{D,T}) P_j(e_j, t)$$



ALADIN LAEF scores



Scores of screen level temperature, relative humidity and 6-hourly total precipitation versus forecast lead time, calculated against SYNOP observations for ECMWF ENS downscaling (black) and new ALADIN-LAEF Phase I (red). Thin lines denote 10% and 90% confidence intervals.



Conclusions and summary

The ALADIN-LAEF system runs operationally on HPCF at ECMWF twice a day with the integration starting at 00 and 12 UTC going up to 72 hours.

The ensemble consists of 1 unperturbed control run and 16 perturbed members involving:

- initial condition (IC) uncertainty,
- model error simulation and
- coupling to perturbed lateral boundary conditions

rendered by ECMWF ENS.



Published papers

Bellus, M., Y. Wang, F. Meier, 2016: Perturbing surface initial conditions in a regional ensemble prediction system. *Mon. Wea. Rev.* 144: 3377-3390.

Wang, Y., M. Bellus, C. Wittmann, M. Steinheimer, F. Weidle, A. Kann, S. Ivatek-Šahdan, W. Tian, X. Ma, S. Tascu, and E. Bazile, 2011: The Central European limited-area ensemble forecasting system: ALADIN-LAEF. *Quart. J. Roy. Meteor. Soc.*, 137, 483–502.

Wang, Y., M. Bellus, J. Geleyn, X. Ma, W. Tian, and F. Weidle, 2014: A new method for generating initial perturbations in regional ensemble prediction system: blending. *Mon. Wea. Rev.* 142: 2043-2059.

Wang, Y., A. Kann, M. Bellus, J. Pailleux, and C. Wittmann, 2010: A strategy for perturbing surface initial conditions in LAMEPS. *Atmos. Sci. Lett.*, 11, 108–113.

Wang, Y., M. Bellus, G. Smet, F. Weidle, 2010b: Use of ECMWF EPS for ALADIN-LAEF. *ECMWF Newsletter*, 126, Winter 2010/2011, 18-22.

Derkova, M., M. Bellus, 2007: Various applications of the blending by digital filter technique in the ALADIN numerical weather prediction system, *Meteorologicky casopis*, 10, 27–36.

Wang, Y., M. Bellus, A. Ehrlich, M. Mile, N. Pristov, P. Smolikova, O. Spaniel, A. Trojakova, R. Brozkova, J. Cedilnik, D. Klaric, T. Kovacic, J. Masek, F. Meier, B. Szintai, S. Tascu, J. Vivoda, C. Wastl, Ch. Wittmann, 2017: 27 years of Regional Co-operation for Limited Area Modelling in Central Europe (RC LACE). *Bulletin of the Am. Met. Soc.*, Vol. 99 Issue 7, 1415-1432.

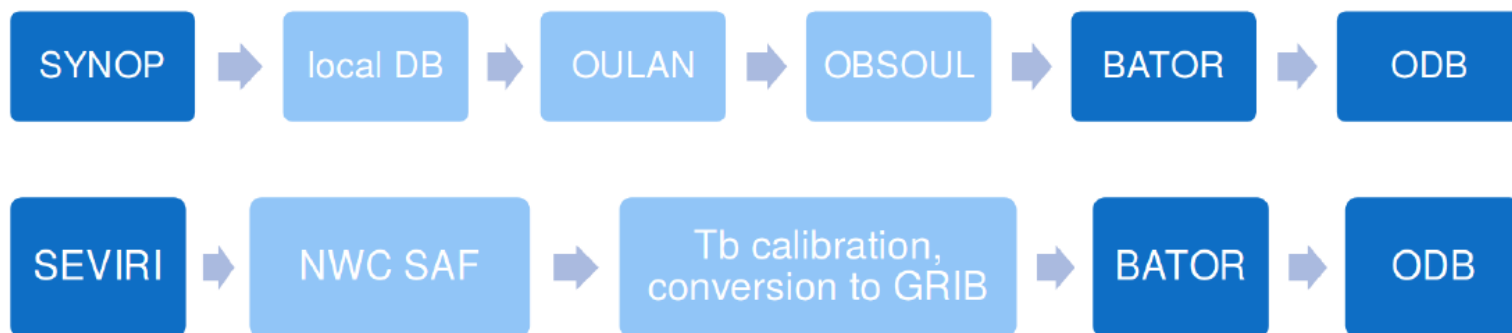


What is OPLACE

A common observation preprocessing system (OPLACE).

- processed and quality checked meteorological observations in an appropriate format for data assimilation in NWP models.
- NMSs exchange their dense national surface synoptic measurements and high-resolution aircraft data in real-time.

OPLACE ensures stable and reliable bases for operational NMS purposes.



Preprocessing steps

data acquisition
GTS / SYNOP

decoding, local DB,
simple QC, format
conversion

time-slot
splitting

obsoul_XXXXXX_xx_YYYYMMDD01

obsoul_XXXXXX_xx_YYYYMMDD02

obsoul_XXXXXX_xx_YYYYMMDD03

obsoul_XXXXXX_xx_YYYYMMDD04

obsoul_XXXXXX_xx_YYYYMMDD05

obsoul_XXXXXX_xx_YYYYMMDD06

obsoul_XXXXXX_xx_YYYYMMDD07

....

data acquisition
EUMETCAST / SEVIRI

calibration &
format conversion

time-slot
splitting

grib_7_seviri_xx_YYYYMMDD01

grib_7_seviri_xx_YYYYMMDD02

grib_7_seviri_xx_YYYYMMDD03

grib_7_seviri_xx_YYYYMMDD04

grib_7_seviri_xx_YYYYMMDD05

grib_7_seviri_xx_YYYYMMDD06

grib_7_seviri_xx_YYYYMMDD07

....

data acquisition
ECMWF/ NWP data

NWC SAF
(cloud information &
format conversion)

Illustration of observation preprocessing steps for synoptic data and SEVIRI radiances.

Observation types

Observations	Type/Sensor	Platform	Format
Surface synoptic	SYNOP, SHIP, BUOY		ASCII, BUFR
Aircraft	AMDAR, ACARS		BUFR
Upper-air sounding	TEMP, TEMP MOBIL		ASCII, BUFR
Wind profiler	EUROPROFILE		BUFR
Atmospheric motion vectors	GEOWIND, HRWIND	Meteosat 10/11	BUFR
Satellite radiances	SEVIRI AMSU-A/B, MHS, HIRS, IASI	Meteosat 10/11 NOAA 15/18/19 Metop-A/B,	GRIB BUFR
Ocean/sea winds	ASCAT	Metop-A/B	BUFR

Overview of observations types, sensors and data formats available in OPLACE.



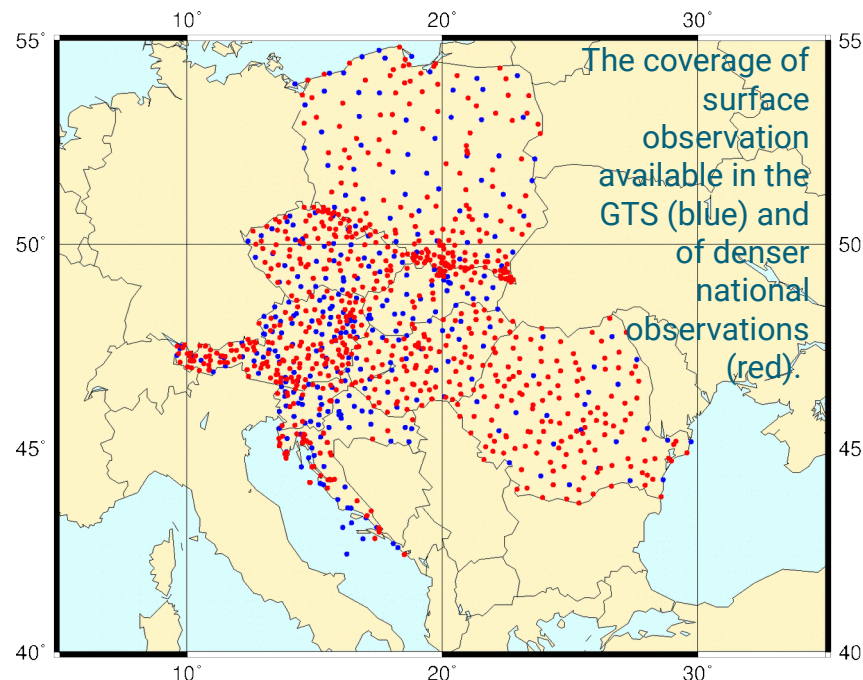
OPLACE – national data



OPLACE national data exchange and access

- high resolution surface synoptic data exchange
- **OPLACE access for non-LACE countries**
 - currently two non-LACE users (Tunisia, Poland)

Number of national stations		Update WRT 2017
Austria	169	-0/+0
Croatia	21	-0/+0
Czech Republic	60	-30/+0
Hungary	93	-2/+3
Romania	134	-0/+0
Slovakia	47	-0/+1
Slovenia	17	-0/+0
Poland	186	-0/+186
Total:	727	



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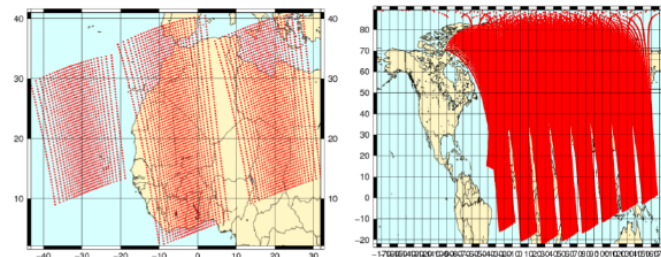
OPLACE - developments



Operational



- **ATOVS data handling corrections for Metop-A**
 - lack of data fixed in February 2018
- **new EUMETSAT prime spacecraft Meteosat-11 (MSG-4) since 20 February 2018**
 - parallel data provision from Meteosat-10/11 till 6 March 2018
 - information and guidelines provided on the RC LACE Forum
<http://www.rclace.eu/forum/viewtopic.php?f=37&t=130&start=140#p1959>
- **coastal winds observations over the oceans from Advanced SCATterometer (ASCAT)**
 - new observations (12.5km resolution) implemented in 26 March 2018
 - validated in collaboration with Benedikt Strajnar
- **corrections for TEMP data processing**
 - workaround to avoid BATOR crash due to too many levels
 - adaptation to merge as much BUFR & ASCII as possible



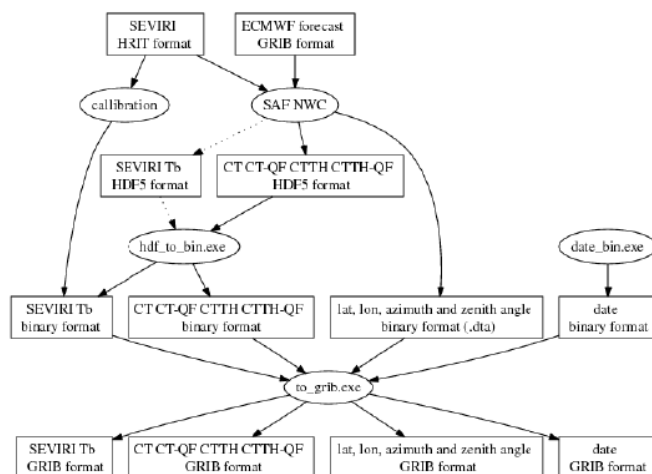
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• redesign of the OPLACE scripts

- more and more data is processed
- complexity of the system is growing
- aim is to improve the operations
 - - parallelization using ecFlow scheduler
 - - more robust to avoid data issues
 - - easier monitoring & supervision



• technical upgrade for SEVIRI

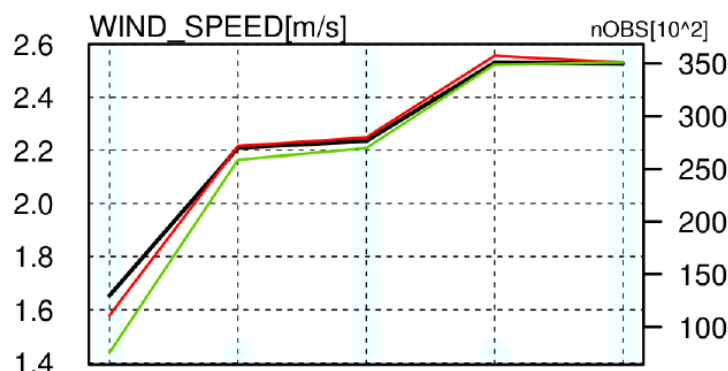
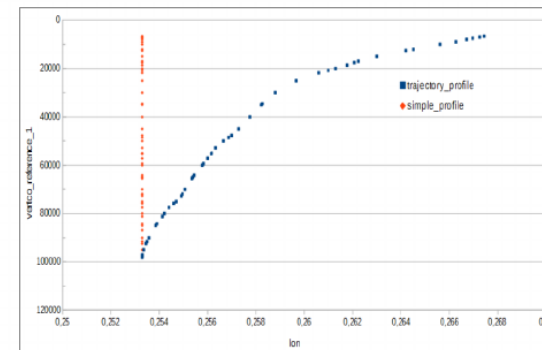
- GRIB format to be replaced by netCDF
- more simple product generation (using python, javac)
- easier porting & more flexible for testing new NWC SAF versions
- courtesy of CMS Lanion

• TAC2BUFR migration

- first prototype of BUFR SYNOP & AMDAR data processing in OPLACE test suite
- further testing & the redesign is needed before operational implementation to avoid delays in OPLACE data provision

• BUFR TEMP handling

- BATOR CY41/CY43 offers the use of updated time & trajectory information
- tested in collaboration with A. Satouri, see Satouri (2017)



- impact on 3DVAR analysis and forecast
 - tested in collaboration with D. Ustuner
 - improved fit to observations at analysis
 - very small positive impact for +6h of wind above 400hPa

OPLACE - ModeS



OPLACE national data exchange and access

- high resolution aircraft data exchange from modern air surveillance systems
 - Mode-S MRAR from ARSO/Slovenia
 - Mode-S EHS from KNMI/Netherlands
 - stable and reliable data provision
- extension by Mode-S MRAR from the Czech Republic - ongoing
- Mode-S EHS from Slovenia and the Czech Republic - ongoing
- negotiation with KNMI about processing our data started (B. Strajnar)
- All Members explore availability of Mode-S data.

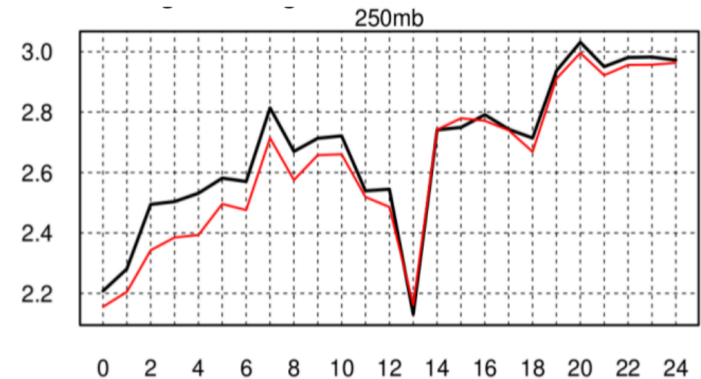
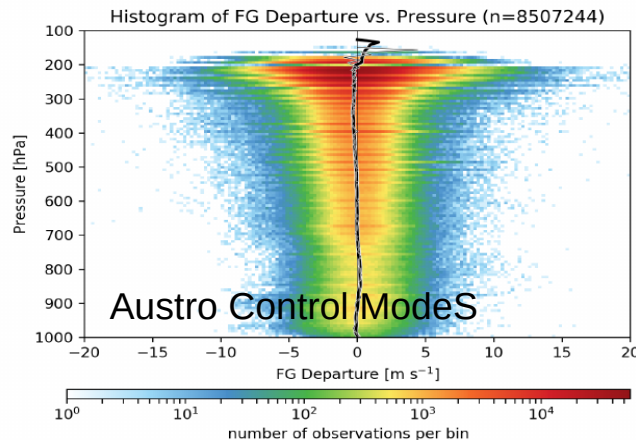
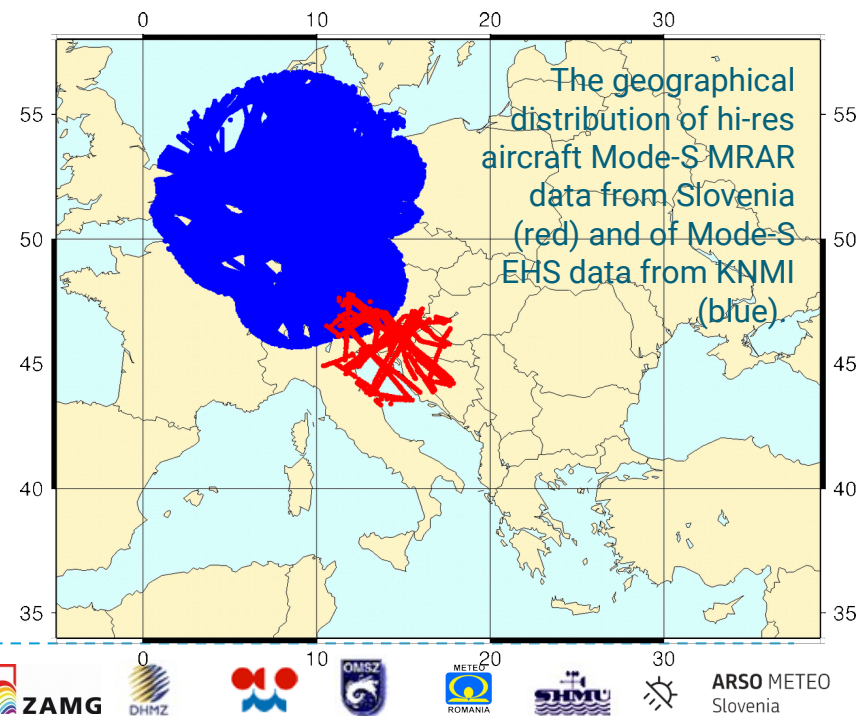
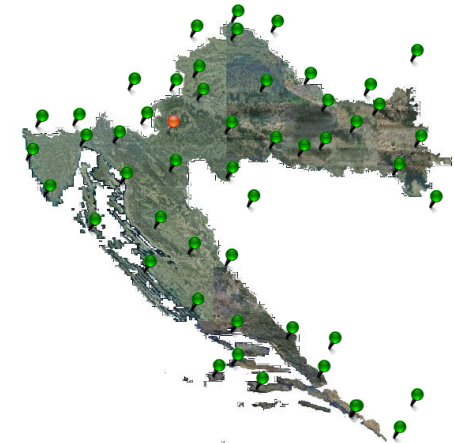
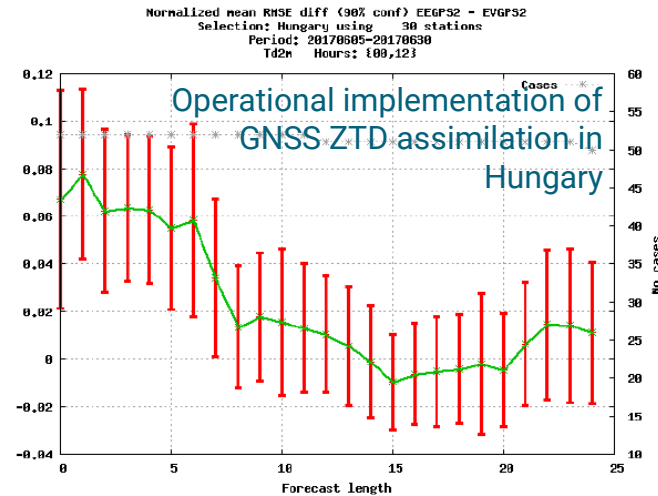
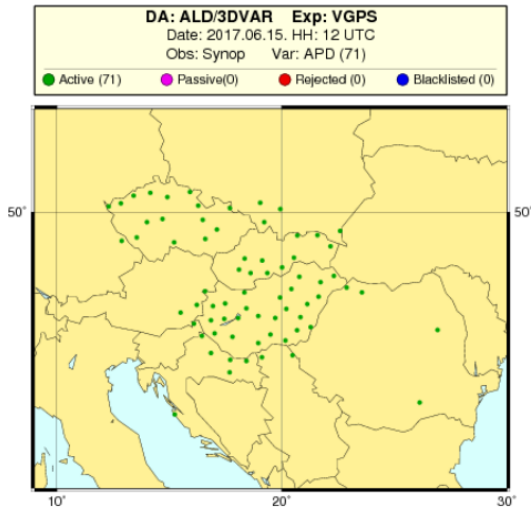


Figure 1: Time evolution of **RMSE for wind speed at 250hPa** verified against aircraft observations for period of 11 Jan – 9 Feb 2017 12UTC. **Reference** and **Mode-S EHS** experiment.



GNSS data



● Priorities for 2019:

- scripts redesign to improve OPLACE operations
- TAC2BUFR migration
- review wind profiler processing
- explore an extension by GNSS
- any other observations ???
- observation monitoring

