

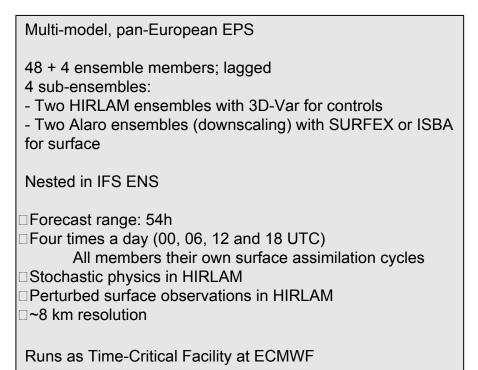
Developments in GLAMEPS and HarmonEPS

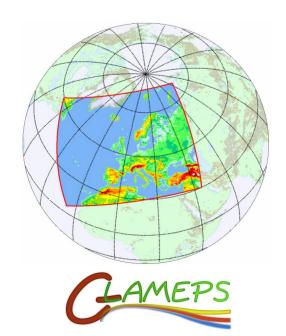
Inger-Lise Frogner

and the HIRLAM EPS and predictability team, and RMI for GLAMEPS

GLAMEPS (version 2, since October 2013)

Operational since 2011





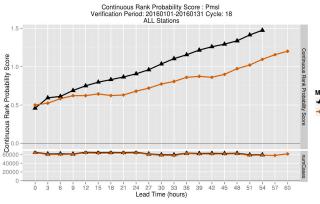




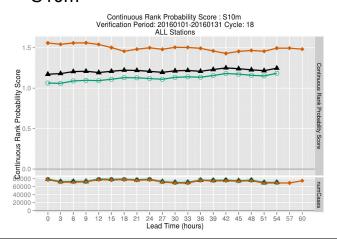
Kai Sattler, Alex Deckmyn, Xiaohua

GLAMEPS (version 2)

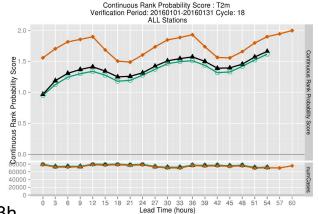




S10m



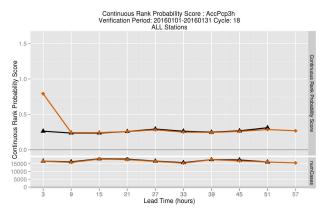
T2m



IFS ENS GLAMEPS raw GLAMEPS cal.

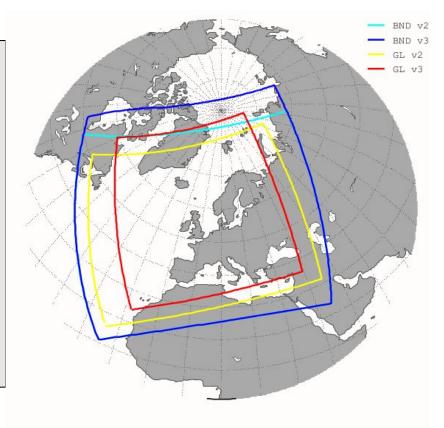
CRPS

AccPcp3h



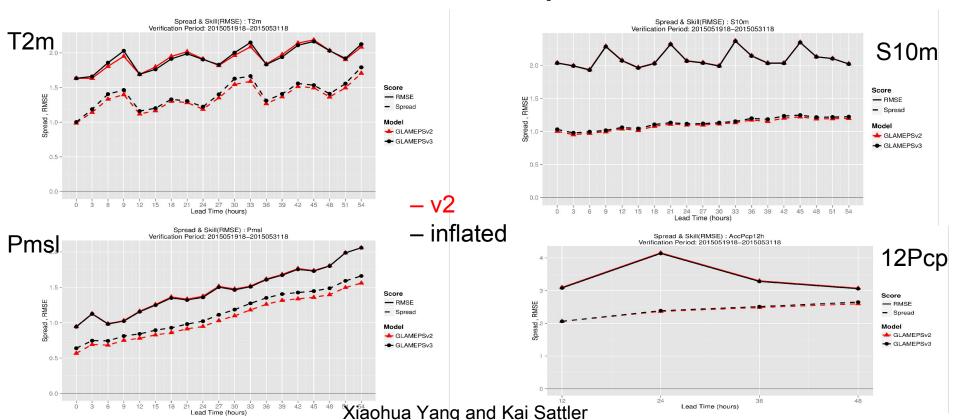
GLAMEPS (version 3, tests ongoing)

- Hourly output
- Increased resolution 0.05 deg. (Hirlam) / 6 km Alaro
- Reduced area
- 36 members (4+1)
- Inflation of the initial perturbations coming from IFS ENS
- Include CAPE SVs in Hirlam
- Changes for ALARO:
 - Upgrade from cy37 to cy38
 - Perturb observations
 - CA?
 - Implement perturbation in horizontal diffusion?
 - Adding inflation factor to ALARO boundary?
- Parallel run ~ May. Aim: replace v2 ~ August

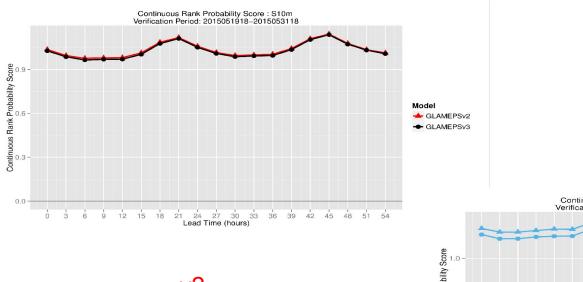




Inflation of initial perturbations in HIRLAM sub-ensembles – spread/skill

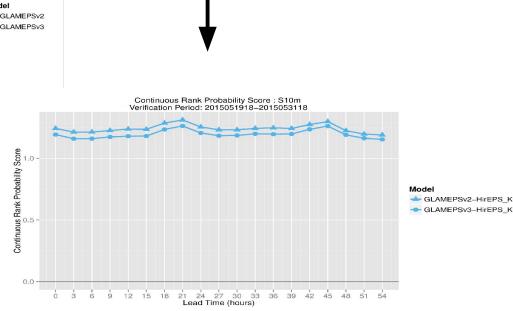


Inflation of initial perturbations in HIRLAM sub-ensembles – CRPS



- -v2
- inflated
- ^^ HirS v2
- . . HirS inflated

Xiaohua Yang and Kai Sattler



Calibrating GLAMEPS

Aim: Make well-calibrated forecasts at all model grid points based on (recent) historical data of

- synop measurements
- forecasts
- orographic and (model) climate information

Operational system:

T₂m

Gaussian distribution with parameters:

- **mean**: ensemble mean + model elevation
- log(standard deviation): log(ensemble standard deviation) + log(model elevation))

S10m

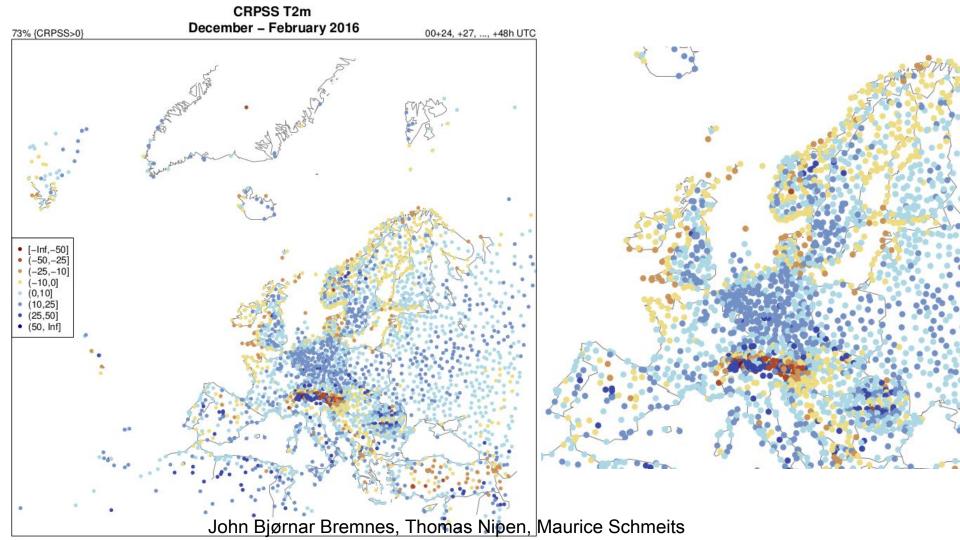
Box-Cox t-distribution with parameters

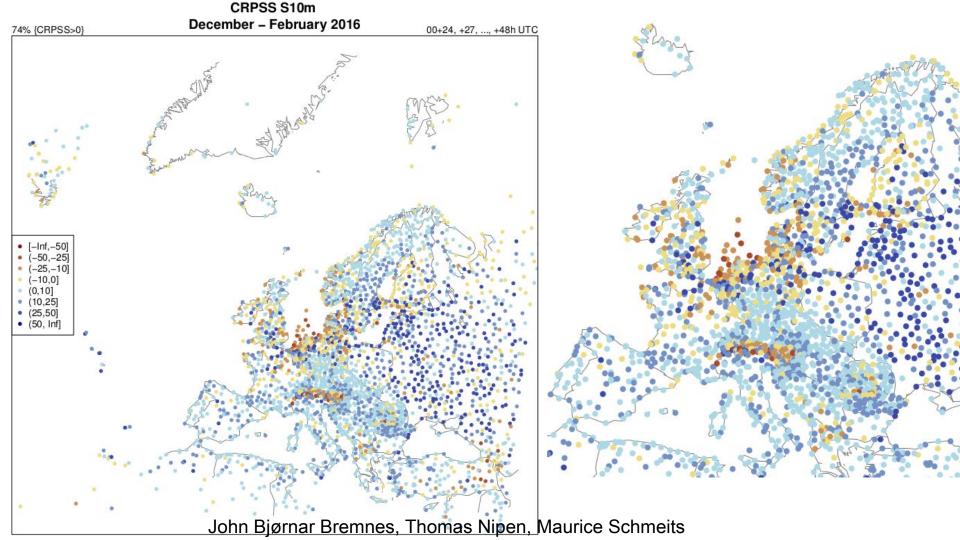
- mean: ensemble mean + model elevation
- log(sigma): log(ensemble standard deviation) + log(max{1,model elevation})
- nu: ensemble mean
- log(tau): constant

Training

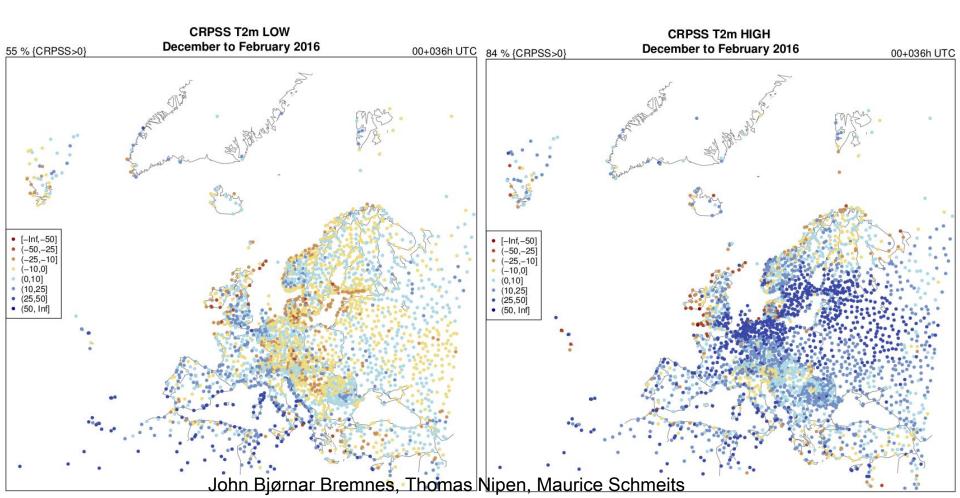
- separate models for each forecast hour and lead time
- models updated every Thursday at approx. 05 UTC
- estimation time about 2 hours (T2m) and 5.5 hours (S10m)
- training period of 42 days (max. 20000 cases)
- no lagging

John Bjørnar Bremnes, Thomas Nipen, Maurice Schmeits





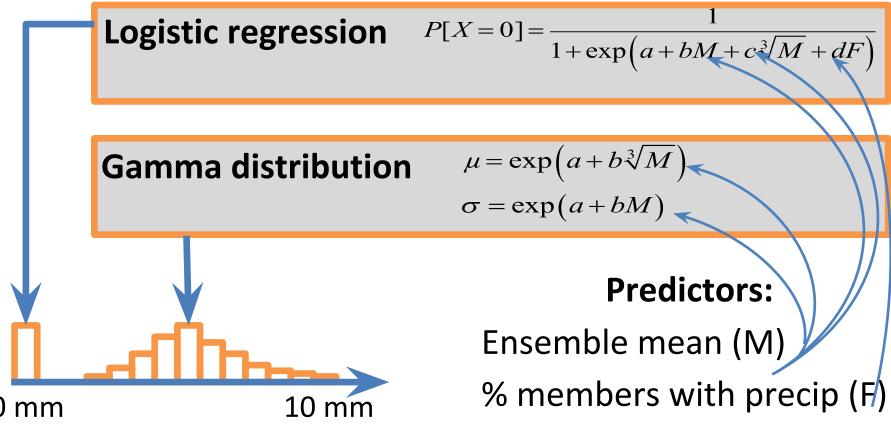
CRPSS when ensemble mean is ...



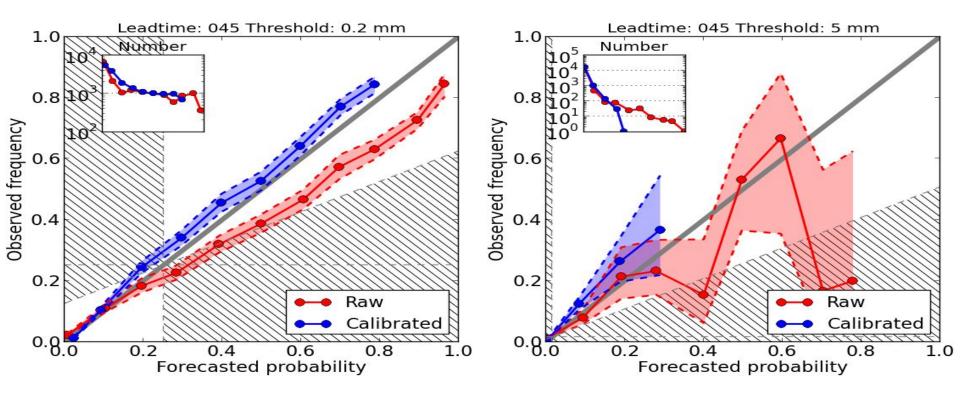
Current work

- better modeling of spatial variations:
 - a. Use flexible regression methods to predict spatial bias using training sample errors, orography and climate information
 - b. use output from a) as input to the "probabilistic" regression model
- precipitation calibration

Zero-adjusted Gamma distribution



John Bjørnar Bremnes, Thomas Nipen, Maurice Schmeits



John Bjørnar Bremnes, Thomas Nipen, Maurice Schmeits

Experimental – first operational version expected in 2016

For European areas

Configurations vary, but typically between 10+1 and 20+1 members

Arome and Alaro

2.5 km

3D-Var

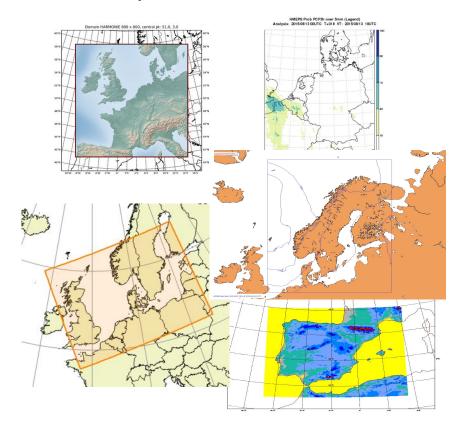
SURFEX

+36h

All members have their own surface assimilation cycles

Nested in IFS ENS or IFS high res.

Experiments with perturbations in initial conditions, lateral boundary conditions, model physics and surface ongoing.



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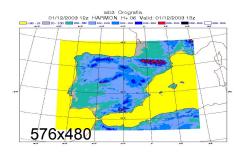
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γSREPS: talk by José A. Garcia-Moya



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SURFEX

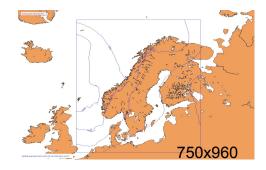
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MEPS: see poster by Ulf Andrae



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3D-Var

SURFEX

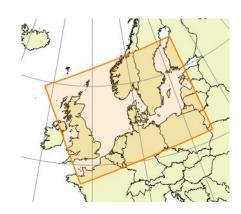
+36h

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COMEPS: see talk by Xigohua Yang



Experimental – first operational version expected in 2016

For European areas

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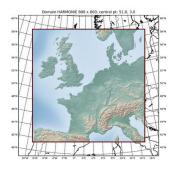
- Arome and Alaro
- 2.5 km
- ₃3D-Var

SURFEX

- ∍+36h
- All members have their own surface assimilation cycles

Nested in IFS ENS or IFS high res.

Experiments with perturbations in initial conditions, lateral boundary conditions, model physics and surface ongoing.



Netherlands: ask Jan Barkmeijer for details

Experimental – first operational version expected in 2016

For European areas

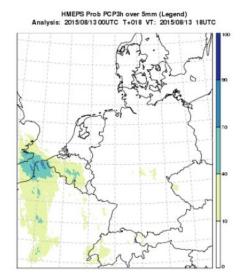
Configurations vary, but typically between 10+1 and 20+1 members

- Arome and Alaro
- 2.5 km
- 3D-Var
- SURFEX
- +36h
- All members have their own surface assimilation cycles

Nested in IFS ENS or IFS high res.

Experiments with perturbations in initial conditions, lateral boundary conditions, model physics and surface ongoing.

HMEPS: running in test mode, RMI
Geert Smet



LBC

Experiments with different flavours of using IFS ENS and SLAF -

see presentation by Andrew Singleton

Initial perturbations

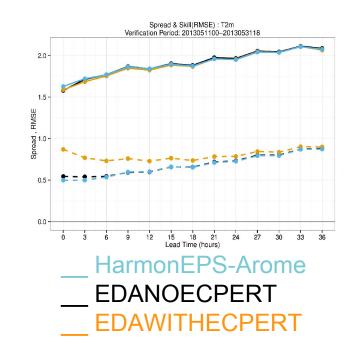
- Default is to use perturbations from IFS ENS/SLAF
- EDA with 3D-Var tested
- LETKF under development

Tested perturbations based on first guess

EDA

10 + 1 member Arome EPS, 21 days in May 2013

- HarmonEPS-Arome: default setup with 3D-Var for control and large scale perturbations from IFS ENS added to this analysis for each member
- EDANOECPERT: Each member running their own analysis, with perturbed observations
- EDAWITHECPERT: same as above, but also added large scale perturbations from IFS ENS

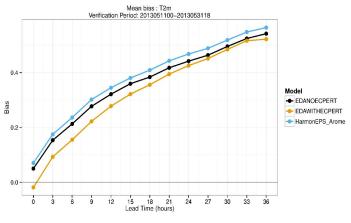


Spread and skill T2m

Inger-Lise Frogner

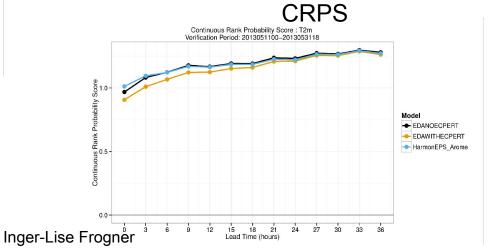
EDA

T₂m



Mean bias



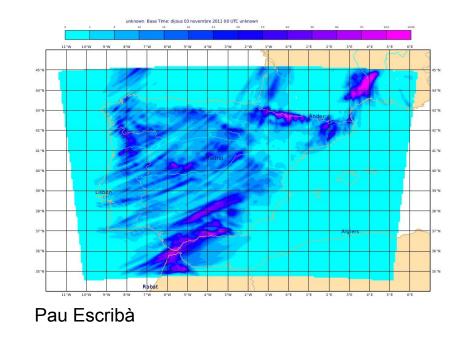




LETKF versus 3DVAR

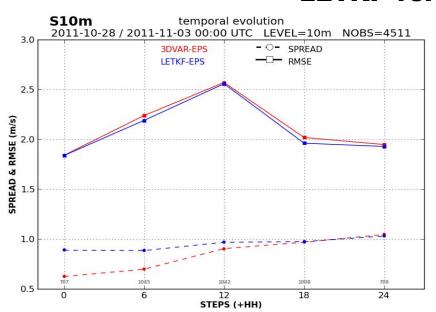
Period of study: 2011102800 – 2011110300 = 7 days, 7 EPS Runs, started
 at 00 UTC every 24 hours up to H+24 over IBERIAN peninsula.

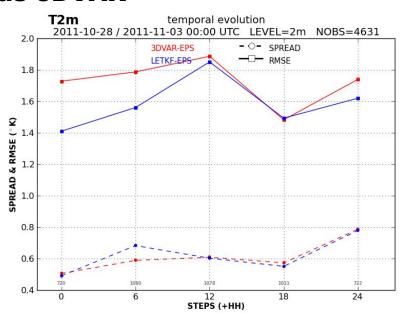
Model domain.
Accumulated
precipitation field
showing the
strong
synoptically
driven
convection



Temporal Evolution of SPREAD and RMSE for sfc params

LETKF versus 3DVAR





Perturbations based on first guess

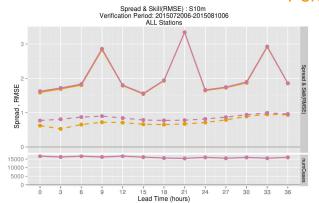
Perturbation of initial state according to: IN = AN_c + k *(FG_c - FG_m) with the hope to retain the small scale information from the members

Spread and skill

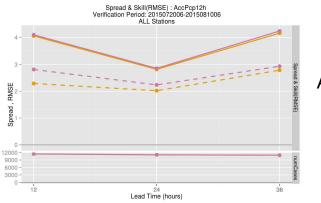
S10m

Pert: First guess
Pert: IFS ENS

Ulf Andrae







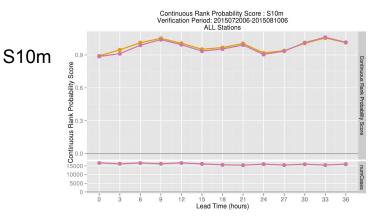
AccPcp12h

T₂m

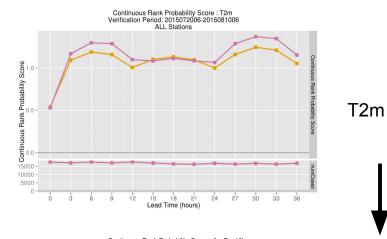
Perturbations based on first guess

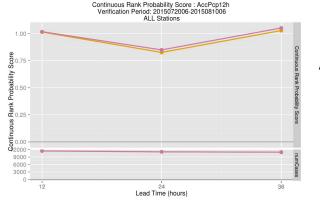
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CRPS Pert: First guess
Pert: IFS ENS



Ulf Andrae





AccPcp12h

Model error

- Default is to use multi-physics with Arome and Alaro
- •SPPT (Alfons Callado, implementation ongoing)
- •Multi-physics the "LAEF-way" see poster by Björn Stensen
- •Cellular Automata (CA) (Lisa Bengtsson, presented last year)
- •Stochastic perturbations in parameterizations / processes (Sibbo van der Veen)
- •Humidity perturbations and MSG cloud mask (Sibbo van der Veen, presented last year)

Surface uncertainty

- •Thanks to MF and F. Bouttier for providing surface perturbation code -> implemented in HarmonEPS (Ole Vignes)
- •Perturb surface parameters, like soil moisture, albedo, SST, ... (Work ongoing, Andrew Singleton and Björn Stensen)
- •Perturb surface physics: study perturbations in momentum, heat and moisture flux parameterizations. (Work ongoing, Andrew Singleton)

Post-processing and HARP EPS developments

HARP:

- Tagging of HARP v1.2 and v2.0
- Work on new formulation of spread/skill and deeper understanding of the practice of centering the ensemble round control (see presentation by Ake Johansson)

Post processing:

- Calibration (Thomas Nipen)
- Neighborhood methods (Andrew Singleton)

Thank you