

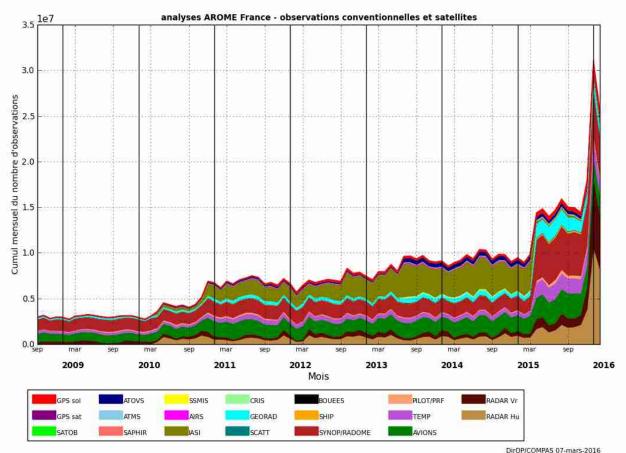
## Outline of talk

- Radar obs assimilation
- 4DEnVar
- Plans: obs, applications



# Evolution of total number of assimilated observations in AROME-France

Evolution des cumuls mensuels de nombre d'observations utilisées par type d'observation



Nov'08: Arome oper with Vr

Spring'10 : Refl oper

Autumn'10: Improved assim of NoRain Refl

Spring'15: 1.3km resol Arome

**Autumn: Higher density radar obs** 



## Use of foreign data; OPERA; plans

- Tested impact of foreign radars (Spain): beneficial
- Wish to implement OPERA data directly in AROME
- => requirements for ODIM-HDF5
- Both raw data and cleaned data are required
- Quality flags have to contain the identification of anomalies and the quantification of the quality for an optimal use in NWP

- •Near future : improve obs operator (DPOL, X-band),
- •Implement some foreign radars in e-suite (D, Be, NL),
- Increase number of radar data in screening in next e-suite,
- Assess importance of initializing precipitating hydrometeors (DPOL)



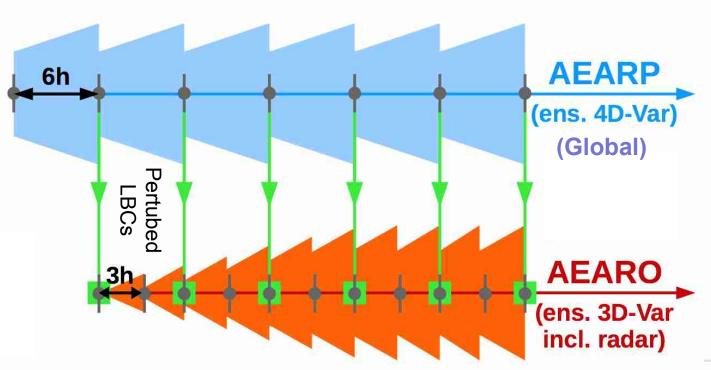
### **EnVar for ARPEGE or AROME: perturbations**

Use an ensemble data assimilation (EDA) with *L* members to compute background perturbations :

$$\delta \widetilde{\mathbf{x}}_{p}^{b} = \frac{1}{\sqrt{L-1}} (\widetilde{\mathbf{x}}_{p}^{b} - \langle \widetilde{\mathbf{x}}^{b} \rangle) \longrightarrow \widetilde{\mathbf{B}} = \frac{1}{L-1} \sum_{p=1}^{L} (\widetilde{\mathbf{x}}_{p}^{b} - \langle \widetilde{\mathbf{x}}^{b} \rangle) (\widetilde{\mathbf{x}}_{p}^{b} - \langle \widetilde{\mathbf{x}}^{b} \rangle)^{\mathsf{T}}$$

- Explicit obs. perturb.
- Implicit Bckgd perturb.

- Explicit obs. and LBCs perturb.
- Implicit bkgd perturb.



Fisher 2003 ; Kucukkaraca and Fisher (2006); Berre et al 2006

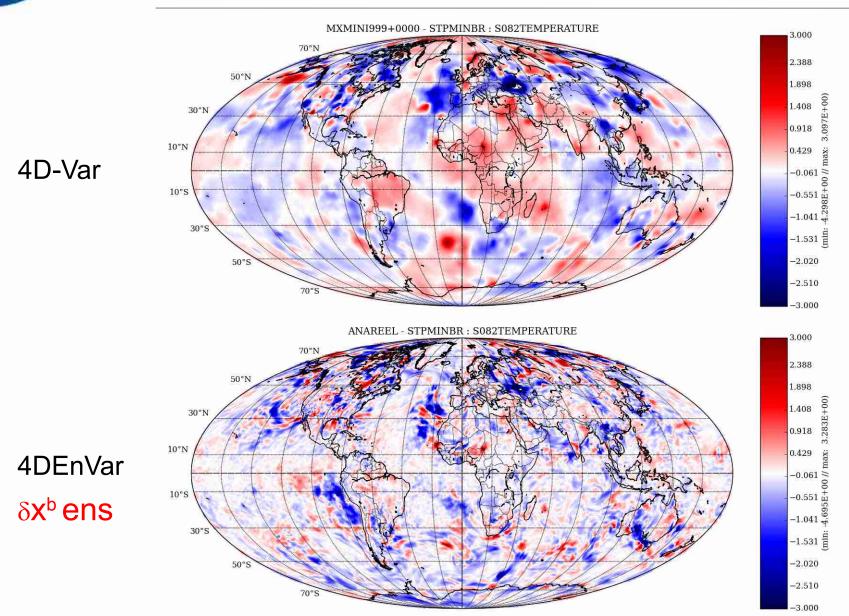
METEO FRANCE

## Comparison of 4D-Var / 4DEnVar formulations for ARPEGE

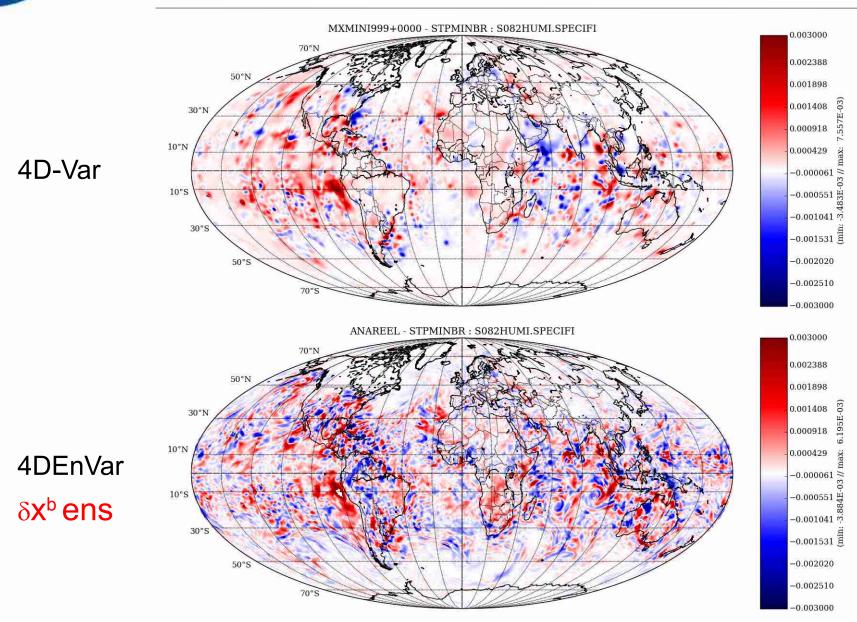
- deterministic 4D-Var at Météo-France
- already uses an ensemble to evolve  $\mathbf{C}_0$  (auto-correlations).
- wavelet representation of **C**<sub>0</sub><sup>w</sup>: provides smoothed correlations.
- covariances evolve implicitly with time :  $\mathbf{B}_{k} = \mathbf{M}_{k} \mathbf{K}_{0}^{b} \Sigma_{0}^{b} \mathbf{C}_{0}^{w} \Sigma_{0}^{bT} \mathbf{K}_{0}^{bT} \mathbf{M}_{k}^{T}$ .
- 4DEnVar using evolved  $\delta \mathbf{x}^{b}$  perturbations derived from an ensemble of fcts
- Ensemble of L=150 members.
- In the present tests, the 150 members also are used to generate the  ${\bf B}_0$  "climatological" matrix for 4D-Var.



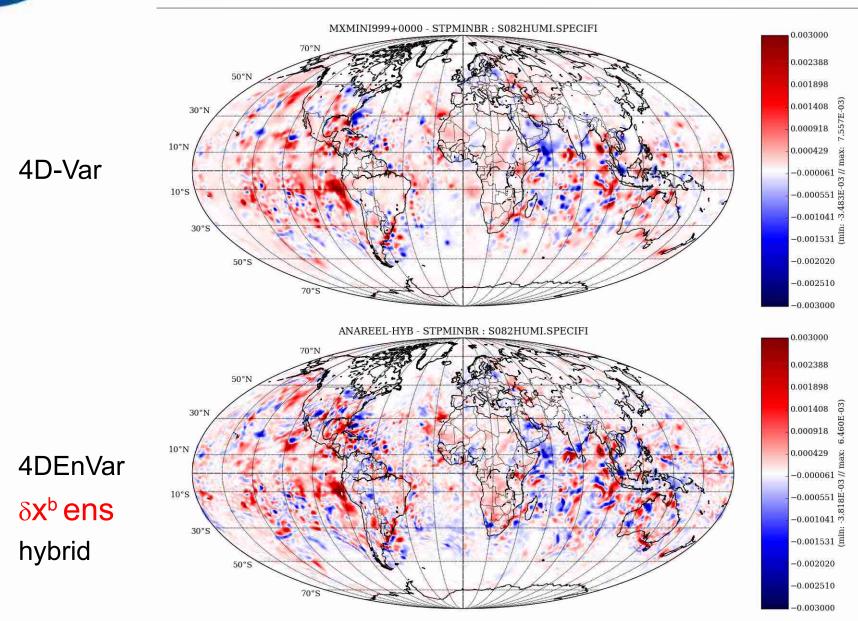
## Comparison 4D-Var / 4DEnVar " $\delta x^b$ ens" (L = 150) Temperature increment at $t_0$ and ~ 850 hPa



## Comparison 4D-Var / 4DEnVar " $\delta x^b$ ens" (L = 150) Specific humidity increment at $t_0$ and ~ 850 hPa



## Comparison 4D-Var / 4DEnVar " $\delta x^b$ ens" (L = 150) Specific humidity increment at $t_0$ and ~ 850 hPa

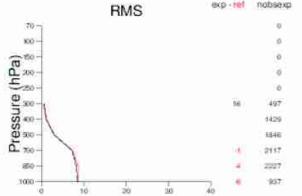


### 4D-Var / 4DEnVar 150 δxb « ens » hybrid

#### TEMP q NH

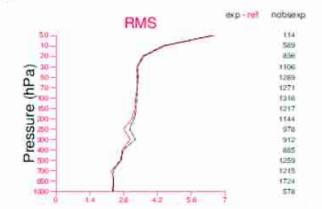
86KL \ref: 86BQ 2013122006-2013122012(06) TEMP-q N.Hemis Used q

### δx<sup>b</sup> ens



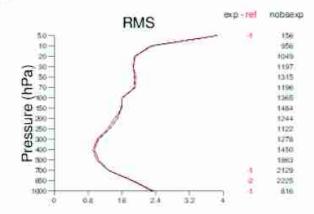
#### 40

86KL \ ref: 868Q 2013122006-2013122012(06) TEMP V NH TEMP-Vwind N.Hemis Used V



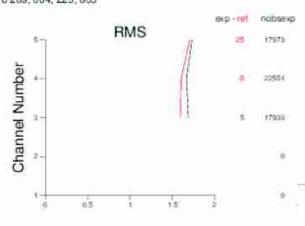
#### **TEMP T NH**

86KL \ref: 86BQ 2013122006-2013122012(06) TEMP-T N.Hemis Used T



#### 86KL \ref: 86BO 2013122006-2013122012(06) TOVS-1C AMSU-B MHS N.Hemis Used Tb 209, 004, 223, 003

#### **AMSUB NH**







#### Overview about EnVar

#### 4DEnVar ARPEGE/AROME already possesses quite a few options:

- $\checkmark$  Renormalize perturbations using a filtered  $\sigma^b$  field.
- ✓ B hybrid.
- Change of variable in order to allow a unique localization.
- Advection of localization.
- ✓ Advection of the so-called "climatological" B.
- ✓ Optimizations to decrease the numerical cost of the localization ("spectral").
- ✓ Various possible formulations for the localization.
- ✓ Reminder: all this is coded starting from the OOPS/C++ layer.

#### State-of-the-art results with 4DEnVar ARPEGE

- Obstats scores to read with some caution.
- ✓ Randomized B tested in 4DEnVar against pure ensemble B: "ens" version seems better than "rand".
- ✓ Increments of 4D-Var and 4DEnVar still look quite different.
- √ 4D aspects require more studies and optimization.



## Strategy for further testing for 4DEnVar in ARPEGE

- ✓ Which size of ens is needed, which one is tractable on HPC?
- Ensemble generation methods.
- ✓ Test 4DEnVar in T149.
- Hybridization seems necessary and promising.
- ✓ Obtain a quasi-optimal and cheap localization approach.
- Use all available observations.
- Add VarBC.
- √ 4D aspects, external loops, initialization.
- ✓ Port VAR prototypes to OOPS-IFS based on CY42R3
- Documentation.



#### Plans for observations in ARPEGE and AROME

- ✓ assimilation of Lidar winds from ADM-AEOLUS (provided these data are made available by Eumetcast dissemination),
- ✓ assimilation of new scatterometer data (ScatSat),
- ✓ get prepared for using data from IRS/MTG,
- ✓ consider new satellites: China (FY3-C, FY3-D), ATMS and CrIS obs. from JPSS1 (USA, successor of Suomi-NPP),
- ✓ AROME:
  - ✓ start using radar data provided by OPERA (technical throughput enabling to monitor a few OPERA radars should be available by the end of 2016)
  - ✓ study the potential of Mode-S data (ASD-B format),
  - ✓ all-sky microwave radiances using a Bayesian inversion approach,



## Plans for MF's NWP applications in a general overview

- ✓ Migration to new BULL HPC Phase 2 (ongoing)
- √ Transfer to operations of Arome-EPS (2.5kmL90, 12 members, twice a day)
- ✓ Next E-suite: starting mid 2016 (CY42\_op1?), includes a new convection scheme and Surfex in Arpège; operational switch beginning of 2017
- **✓** 2017-2018 :
  - ✓ Arome-EDA,
  - ✓ Arome-EPS 4 times/day,
  - ✓ Arpège new resolution (about 5km over Western Europe),
  - ✓ very likely also an increase of the horizontal resolution of Arpège EDA and EPS,
  - ✓ GRIB2, etc.



### End of the talk

✓ Obrigado pela sua atenção. Questões por favor.



## Present configuration of the operational global assimilation in ARPEGE

#### deterministic 4D-Var:

- ✓ Time window of 6 h.
- ✓ 2 external loops:
  T1198 C2.2 (7.5 km min) L105 / T149 (~135 km), T399 (~ 50 km).
- ✓ Jc-DFI, VarBC.
- $\checkmark$  **B**<sub>0</sub><sup>1/2</sup> = **K**<sub>0</sub><sup>b</sup>  $\Sigma$ <sub>0</sub><sup>b</sup> **C**<sub>0</sub><sup>1/2</sup>, **C**<sub>0</sub> in wavelet, **K**<sub>0</sub><sup>b</sup> = spectral + NL balances.

#### ensemble assimilation:

- √ 25 perturbed 4D-Vars.
- √ 1 external loop T479 C1.0 (40 km) / T149 C1.0.
- ✓ multiplicative inflation of perturbations applied to the 3h fcts.
- $\Sigma_0^b$  filtered, with the last 25 perturbations and updated every 6 h.
- $\triangleright$  **C**<sub>0</sub> wavelet with the 6 x 25 last perturb. 3h (30 h), updated every 6 h.



#### **EnVar for ARPEGE or AROME: formulation**

From these L sampled perturbations, a localized  $\mathbf{B}_{e}$  is computed

$$\mathbf{B}_{e} = \widetilde{\mathbf{B}} \circ \mathbf{C} = \mathbf{X}^{b} \mathbf{X}^{b^{T}} \circ \mathbf{C}$$
$$\mathbf{X}^{b} = \left[\delta \widetilde{\mathbf{x}}_{1}^{b}, \dots, \delta \widetilde{\mathbf{x}}_{L}^{b}\right]$$

with:

The localization matrix **C** aims at reducing sampling noise by

blam ping sionalifance: with

$$\mathbf{C} = \begin{pmatrix} \mathbf{I}_{N} \\ \vdots \\ \mathbf{I}_{N} \end{pmatrix} \mathcal{C}(\mathbf{I}_{N} \dots \mathbf{I}_{N}) = \mathbf{1}_{N} \mathcal{C} \mathbf{1}_{N}^{T}$$

 $I_N$  is a  $N \times N$  identity matrix,  $I_N$  is composed of  $M \times (K+1) I_N$  blocks, and C is a  $N \times N$  correlation matrix